

Concurrent Systems

Nebenläufige Systeme

II. Concurrency

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Outline

Preface

Causality

Interdependencies

Dimensions

Resource Sharing

Principles

Competition

Synchronisation

Summary



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Subject Matter

- discussion on two fundamental **abstract concepts**:

concurrency (Ger. *Nebenläufigkeit*)

- designates the relation of causal independent events
- is related to events that have no mutual influence

causality (Ger. *Kausalität, Ursächlichkeit*)

- designates the relation between cause and effect
- is the causal chain or connection of two events



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Events occur or are concurrent if none is the cause of the other.



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Definition (concurrent)

Events occur or are concurrent if none is the cause of the other.

■ explanation of the relation of these concepts to **resource sharing**

- differentiated with respect to various types of resources and sharing
- classified as to appropriate or necessary synchronisation paradigms



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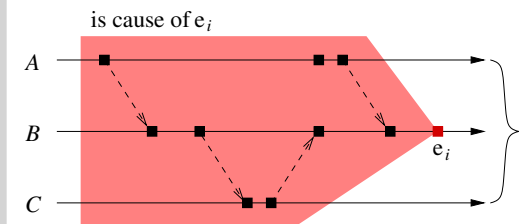
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Principle of Causality

■ causal chain of events related to some other event e_i :

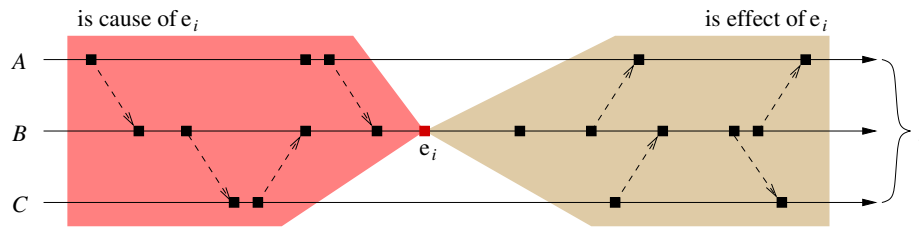


- A , B and C denote some computation on a private or shared processor



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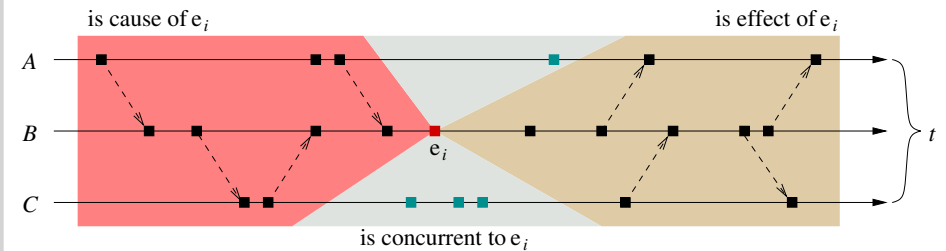


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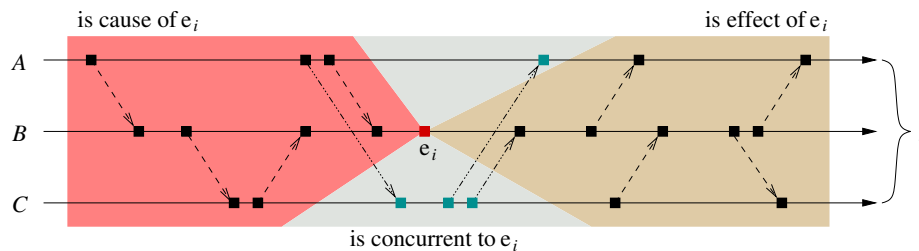


- A , B and C denote some computation on a private or shared processor
- an event is concurrent to another event (e_i) if it lies in the elsewhere of the other event (e_i)
- the event is neither cause nor effect of the other event (e_i)



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- an event is concurrent to another event (e_i) if it lies in the elsewhere of the other event (e_i)
- the event is neither cause nor effect of the other event (e_i)
 - as the case may be, it is cause/effect of other events (different from e_i) that are lying in the elsewhere (cf. dash-and-dot line)



Order of Precedence

- computations can be carried out concurrently provided that:
 - general** ■ none requires a result of the other (cf. p. 10)
 - non-existent **data dependencies**



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 - deadlines may be missed rarely or under no circumstances
 - periods may be stretched up to a certain limit or not at any time
 - non-existent **timing restrictions** \leadsto *real-time processing*



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- interrelation of computations/events constrains concurrency

Event correlations v. Processing modes

“is cause of”
“is effect of” } \mapsto **sequential** (realised before/at run-time)

“is concurrent to” \mapsto **parallel** (realised in logical/real terms)



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\hookrightarrow decrease of the portion of **sequential code** is an important aspect



Limits in the Degree of Concurrency

- Amdahl's Law [1]: speed-up (*su*) achievable by parallel processors
 - work load remains constant with the varying number of processors
 - aim at reducing overall computation time for a given fixed-size problem



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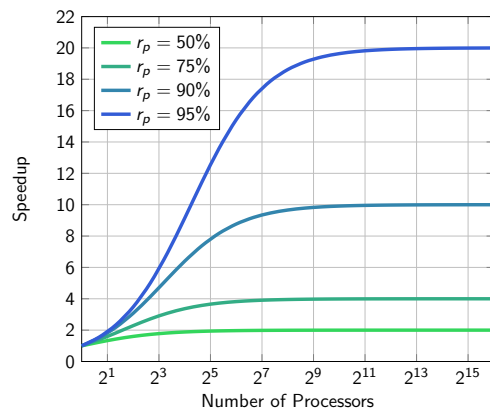
$$su = (r_s + r_p) / (r_s + \frac{r_p}{n})$$

$$= \frac{1}{r_s + \frac{r_p}{n}}$$

r_s ratio of sequential code

r_p ratio of parallel code,
independent of n

n number of processors



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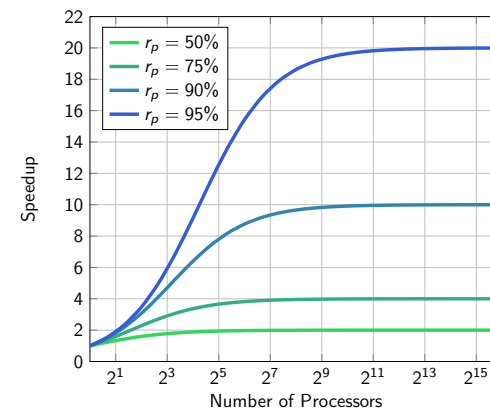
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- speed-up will be constrained by **data management housekeeping**
 - the nature of this overhead appears to be sequential

Adapting the Work Load

- Gustafson's Law [4]: scaled speed-up (ssu), "hands-on experience"
 - work load varies linearly with the number of processors
 - aim at getting better results for a given fixed computation time

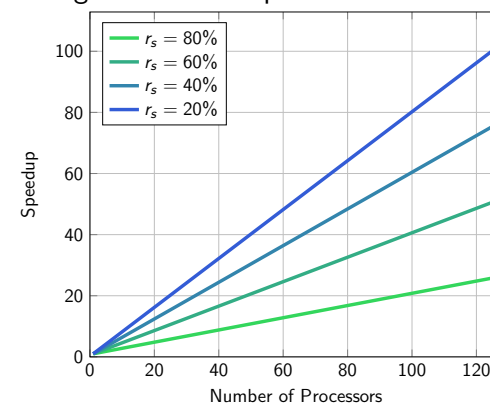
$$ssu = \frac{r_s + r_p \times n}{r_s + r_p}$$

$$= r_s + r_p \times n$$

$$= n + (1 - n) \times r_s$$

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r_s, n as with Amdahl's Law



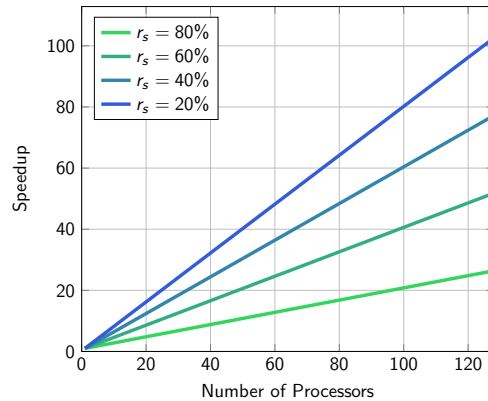
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$$\begin{aligned}ssu &= \frac{r_s + r_p \times n}{r_s + r_p} \\&= r_s + r_p \times n \\&= n + (1 - n) \times r_s\end{aligned}$$

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- data management housekeeping (serial part) becomes less important
 - in practise, the problem size scales with the number of processors: **HPC**¹

¹High Performance Computing



Concurrent Operations of a Computation

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3 int sample(int tuple[2]) {
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6     foo = tuple[0];
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 - 9 and 10
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 - as far as the logical dimension of a program is concerned



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- defined by the **causal order** (Ger. *Kausalordnung*) of the statements
 - as far as the logical dimension of a program is concerned
 - but there is also a **physical dimension**, namely when it comes to the execution of that program by a real processor \leadsto *level of abstraction*



Level of Abstraction

- a concurrent operation (in logical terms) at a higher level can be sequential (in real terms) at a lower level
- a sequential operation (in logical terms) at a higher level can be “concurrent” (i.e., non-sequential in real terms) at a lower level



Level of Abstraction

- a concurrent operation (in logical terms) at a higher level can be sequential (in real terms) at a lower level
 - the operation handles a resource that can be used only consecutively
 - a single memory area that is shared by multiple computations
 - a single communication bus that is shared by multiple processing units
 - simultaneous executions are constrained by the resource characteristic



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 - the n -bit assignment on a $\frac{n}{2}$ -bit machine, with $n = 16, 32, 64$
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²real-time processing, especially in case of hard deadlines.

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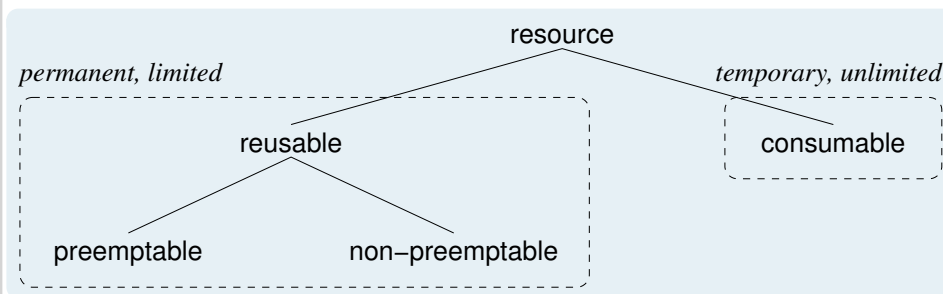
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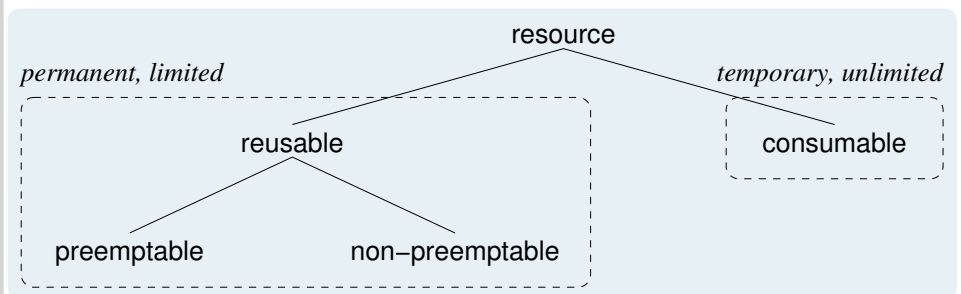
Resource Classification

analogically with [5, 6]



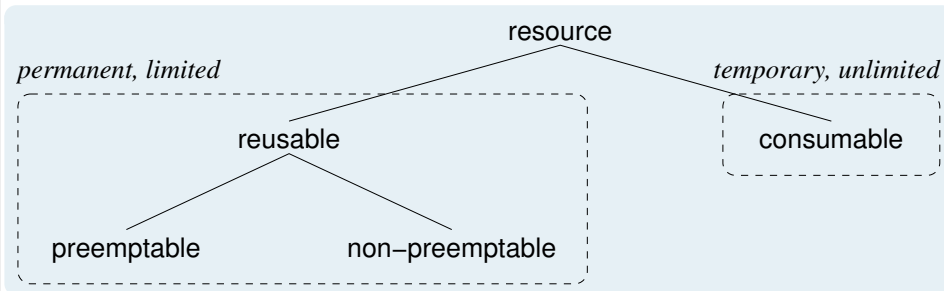
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- permanent³ resources are **reusable**, but always only of limited supply
 - they are acquired, occupied, used, and released (when no longer required)
 - in-use resources** are preemptable or non-preemptable, depending on whether allocation to another occupant is possible
 - when non-preemptable, they are exclusively owned by an occupant

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- temporary resources are of unlimited supply, they are **consumable**
 - i.e. produced, received, used, and destroyed (when no longer required)

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- **hardware resources** as to be managed, e.g., by an operating system

reusable

- processor ■ CPU, FPU, GPU; MMU
- memory ■ RAM, scratch pad, flash
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- reusable and consumable resources imply different **use patterns**



Resource Use Patterns

- if so, **reusable resources** are subject to **multilateral** synchronisation
- **consumable resources** are subject to **unilateral** synchronisation



Resource Use Patterns

- if so, **reusable resources** are subject to **multilateral** synchronisation
 - provided that the following two basic conditions (i.e., constraints) apply:
 - i resource accesses by computations may happen (quasi-) simultaneously
 - ii simultaneous accesses may cause a **conflicting state change** of the resource
 - simultaneous use of a **shared resource** this way must be coordinated
 - coordination may affect computations in a blocking or non-blocking manner⁴

⁴At the same level of abstraction, use of a shareable resource is exclusive in the blocking case or never refused in the non-blocking case.



Resource Use Patterns

- **consumable resources** are subject to **unilateral** synchronisation
 - generally also referred to as logical or conditional synchronisation:
 - logical** – as indicated by the “role playing” of the involved computations
 - conditional** – as indicated by a condition for making computational progress
 - use of a **temporary resource** follows a causal course of events or actions
 - by affecting producers in a non-blocking and consumers in a blocking way



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 - use of a **temporary resource** follows a causal course of events or actions
 - by affecting producers in a non-blocking and consumers in a blocking way
- simultaneous computations **overlap** in time, interfere with each other
 - they become critical in any case if they also overlap in (identical) place

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- assuming that the following subroutines (put and get) are executed in any order and that they may also run simultaneously:

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1 char buffer[80];
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4 void put(char item) {
5     buffer[in++ % 80] = item;
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- put and get must be subject to uni- and multilateral synchronisation
 - they are not concurrent under the assumption that was made above



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- simultaneous computations or operations, resp., are in competition:
 - they compete for the **sharing** of the same reusable resource(s)
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- both aspects, in turn, apply against the background of the following:
 - i the moment of an **simultaneous operation** is not predetermined
 - ii the operation in question is complex (i.e., consists of multiple steps)
 - iii the characteristic of this operation is its **divisibility** in temporal respect



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- the chosen synchronisation method should be **minimally invasive**



Divisibility in Temporal Respect

- when the steps of a complex operation may overlap at run-time
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 - as compiled from C to ASM (x86): `gcc -O3 -m32 -static -S`

in++

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2 leal 1(%ecx), %eax
3 movl %eax, _in
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out++

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- the critical case may result in **wrong reading** (Ger. *Zählerwert*) of in/out
– in++ or out++ are not concurrent to oneself, resp.: they are **not re-entrant**

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Establishing of Synchronism

cf. p. 28

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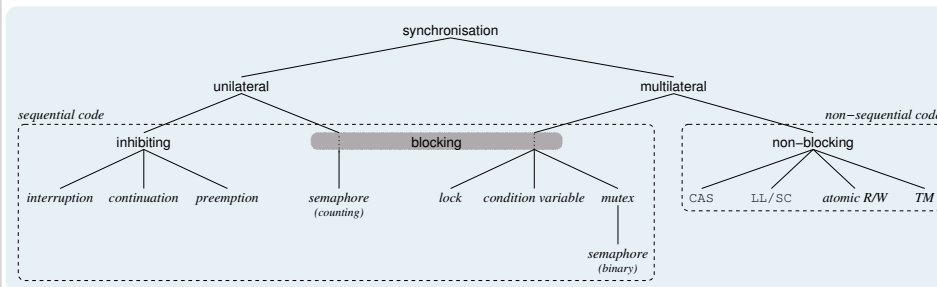
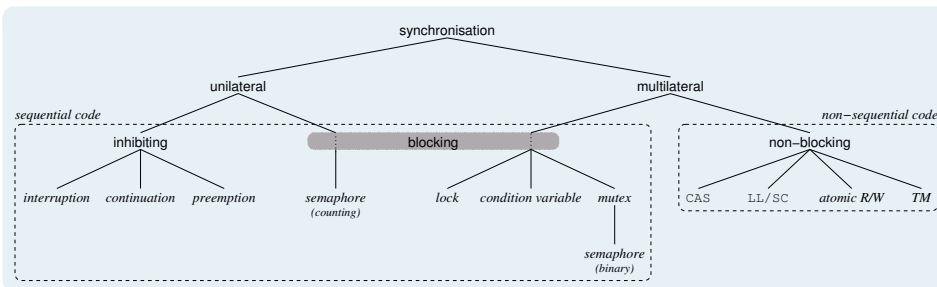
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 - ensure synchronism at **operation start**
 - lock potential overlapping out in the first place
 - synchronised operation is made of sequential code
 - non-blocking**
 - ensure synchronism at **operation end**
 - allow potential overlapping, achieve consistency afterwards
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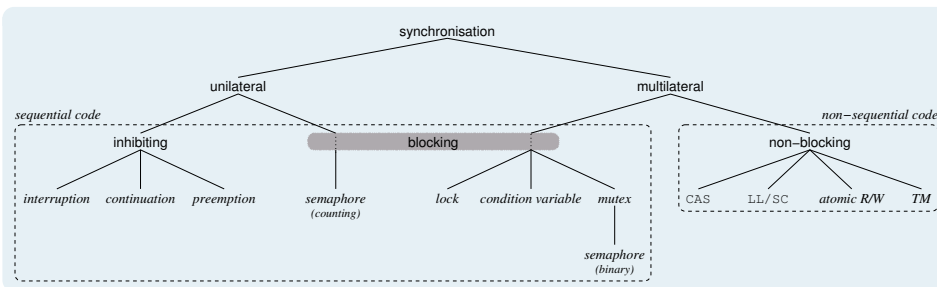
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- both approaches come in a variety of solutions to the same problem

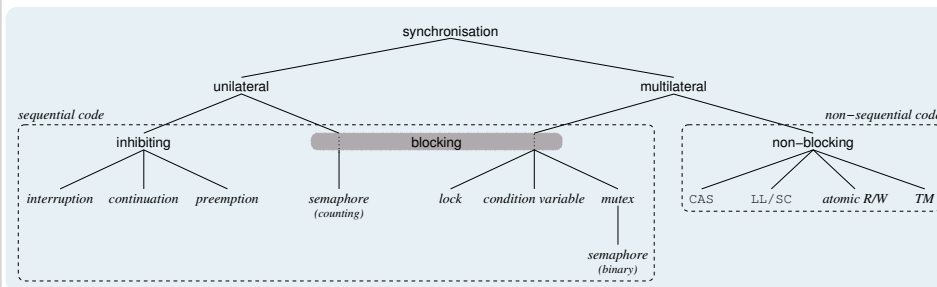
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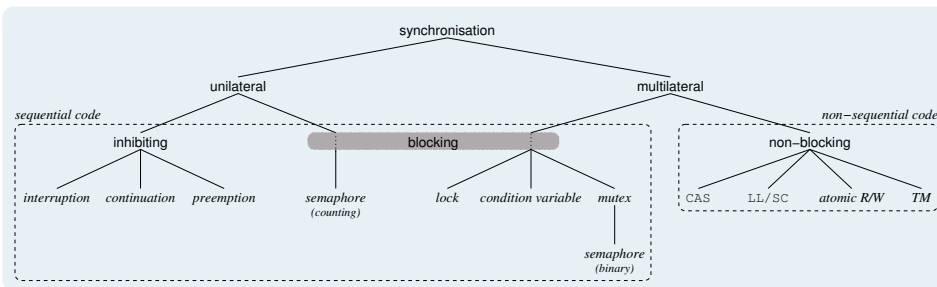
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- wherever applicable, **downsizing sequential code** is basic
 - i.a. Amdahl's Law (cf. p. 8) argues for non-blocking synchronization



- effect of synchronisation procedures on the computations involved



Synchronisation Behaviour

- effect of synchronisation procedures on the computations involved:
 - inhibiting**
 - prevents other computations from launching
 - irrespective of the eventuality of co-occurrence
 - applies to consumable resources, only
 - running computations are not delayed



Synchronisation Behaviour

- effect of synchronisation procedures on the computations involved:

- blocking**
 - delays computations subject to resource availability
 - takes effect only in case of co-occurrence (overlapping)
 - applies to reusable and consumable resources
 - running computations are possibly delayed



Synchronisation Behaviour

- effect of synchronisation procedures on the computations involved:
 - non-blocking** ■ may force non-dominantly running computations to repeat
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 - dominantly running computations are not delayed



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 - where possible, non-blocking synchronisation should be the first choice



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 - where possible, non-blocking synchronisation should be the first choice
- but even then: there is no all-in-one approach for every purpose. . .



Outline

Preface

Causality

Interdependencies

Dimensions

Resource Sharing

Principles

Competition

Synchronisation

Summary



- understanding (Ger.) **Gleichzeitigkeit** in its various meanings



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 - concurrency
 - happening together in time and place [7]
 - designates the relation of causal independent events
 - when none computation depends on results of the other



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 - but simultaneity may also cause overlapping that must be constrained
- synchronism ensures that overlapped complex operations do right
 - the individual sub-steps will be strictly executed *interim* (consecutively) or
 - a *transaction* will take care for consistent (pseudo-) parallel execution



Relativity of Simultaneity

Physics figuratively

- the concept of (distant) simultaneity is not absolute, but depends on the **frame of reference** (Ger. *Bezugssystem*) an observer takes
 - moving- and fixed-platform thought experiment [2, p. 768]:

The simultaneity of two distant events means a different thing to two different observers if they are moving with respect to each other.



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 - a simplistic operation (++) at a higher level may translate to a complex operation (*read-modify-write*) at a lower level
 - while multiple invocations of the former will take place sequentially,⁷ the corresponding ones of the latter may come about non-sequentially
 - while multiple invocations of the latter discretely can be concurrent, their logical correlation to the former makes them possibly not concurrent

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 - operations must be resolved **cross-level** (from “fixed platform” observed) in order to realise their ability for concurrency or need for synchronism

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Résumé

- computations can be **concurrent** if none needs a result of the other
 - they must be free of data and control-flow dependencies
- in order to be concurrent, computations must be **simultaneous**
 - quasi-simultaneous through partial virtualization (hardware multiplexing) or real simultaneous by multiprocessing (hardware multiplication)
 - both techniques will induce computations to overlap in time and place
- **overlapping** in time cause interference but is the lesser of two evils
 - more critical is overlapping **in place** relating to the same resource
 - particularly with regard to the same (i.e., shared) memory area
- critical overlapping must be counteracted through **synchronisation**
 - i.e., coordination of the cooperation and competition between processes
 - here: uni- or multilateral synchronisation, depending on the resource type
- synchronisation ensures for **indivisibility** of a computation cycle
 - at the outset: physical, in blocking manner, by being pessimistic ☹
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Consolidating Example Revisited

cf. p. 16

- **bounded buffer** using a counting semaphore [3] for unilateral and an ELOP (x86) for multilateral synchronisation

```
1 typedef int semaphore_t;          18 char buffer[80];
2                                  19 unsigned in = 0, out = 0;
3 extern void P(semaphore_t*);      20
4 extern void V(semaphore_t*);      21 void put(char item) {
5                                  22     P(&free);
6 semaphore_t free = 80;            23     buffer[fai(&in) % 80] = item;
7 semaphore_t empty = 0;            24     V(&empty);
8                                  25 }
9 static inline int fai(int *ref) {  26
10     int aux = 1;                  27 char get() {
11                                  28     char item;
12     asm volatile("lock; xaddl %0,%1"  29
13     : "=r" (aux), "=m" (*ref)         30     P(&empty);
14     : "0" (aux), "m" (*ref));         31     item = buffer[fai(&out) % 80];
15                                  32     V(&free);
16     return aux;                      33
17 }                                  34     return item;
                                   35 }
```

- free** ■ controls the number of unused buffer entries
 - *P* prevents from buffer overflow, *V* signals reusable resource
- empty** ■ controls the number of used buffer entries
 - *P* prevents from buffer underflow, *V* signals consumable resource
- fai** ■ indivisibly *fetch and increment* specified counter variable

