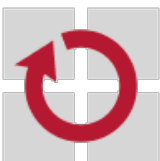


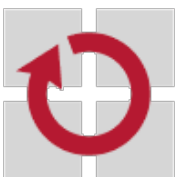
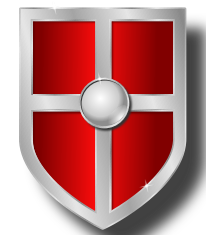
RT-LAGC: Fragmentation-Tolerant Real-Time Memory Management Revisited

Isabella Stilkerich, Michael Strotz, Christoph Erhardt,
Michael Stilkerich



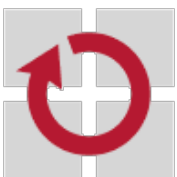
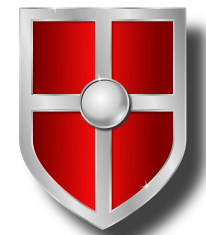
Real-Time Embedded Java

- **Productivity**
- **Safety**
 - Software-based memory protection
- **Efficiency**
 - Ahead-of-time compilation
 - Static configuration



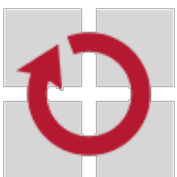
Real-Time Embedded Java

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 - Software-based memory protection
- **Efficiency**
 - Ahead-of-time compilation
 - Static configuration
- **... Memory management?**
 - In particular: predictability?



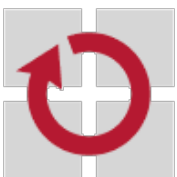
Real-Time Memory Management

- **Pseudo-static allocation** (ImmortalMemory)
 - Bump pointer
 - No memory release



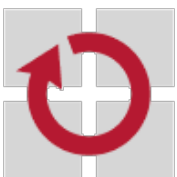
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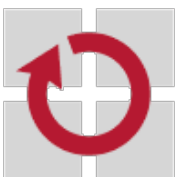
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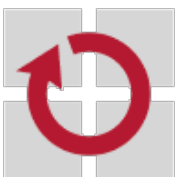
Real-Time Memory Management

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 - Bump pointer
 - Region released as a whole
- } Simple, predictable, special-purpose
- **Automatic memory management**
 - Complex, list-like heap structure
 - Garbage collection
 - Heap fragmentation, unpredictable allocation times
 - Unpredictable latencies

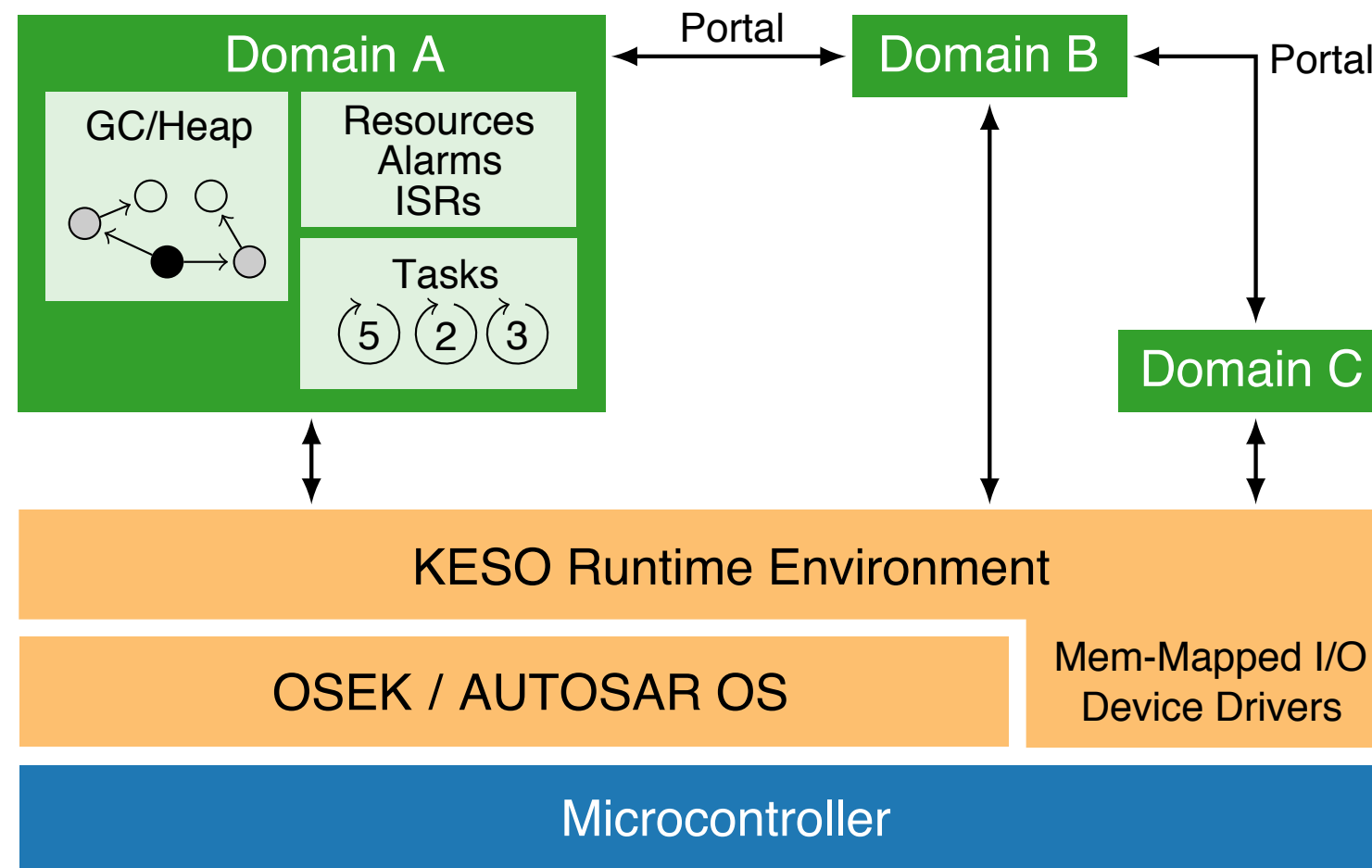


Agenda

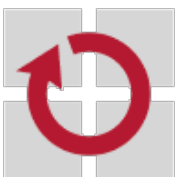
- **Goal: real-time-capable automatic memory management**
 - Bounded allocation times
 - Bounded latencies
 - Good throughput
- **Implementation in the KESO JVM**
 - *Real-Time Latency-Aware Garbage Collection*
- **Evaluation**



The KESO JVM



- Ahead-of-time compilation to C code
- Static configuration
- “Pay only for what you use”



Garbage Collectors in KESO

1. No GC

2. Slack-based mark-and-sweep GC

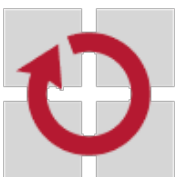
a) Stop-the-world

- Not preemptible

b) Incremental

- Preemptible by application tasks
- Synchronisation, write barriers

- **Configurable per domain**



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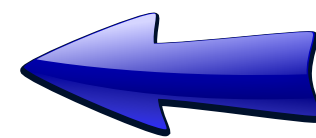
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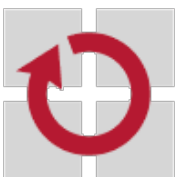
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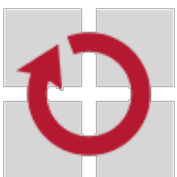


Extend for better
predictability



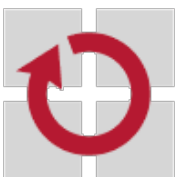
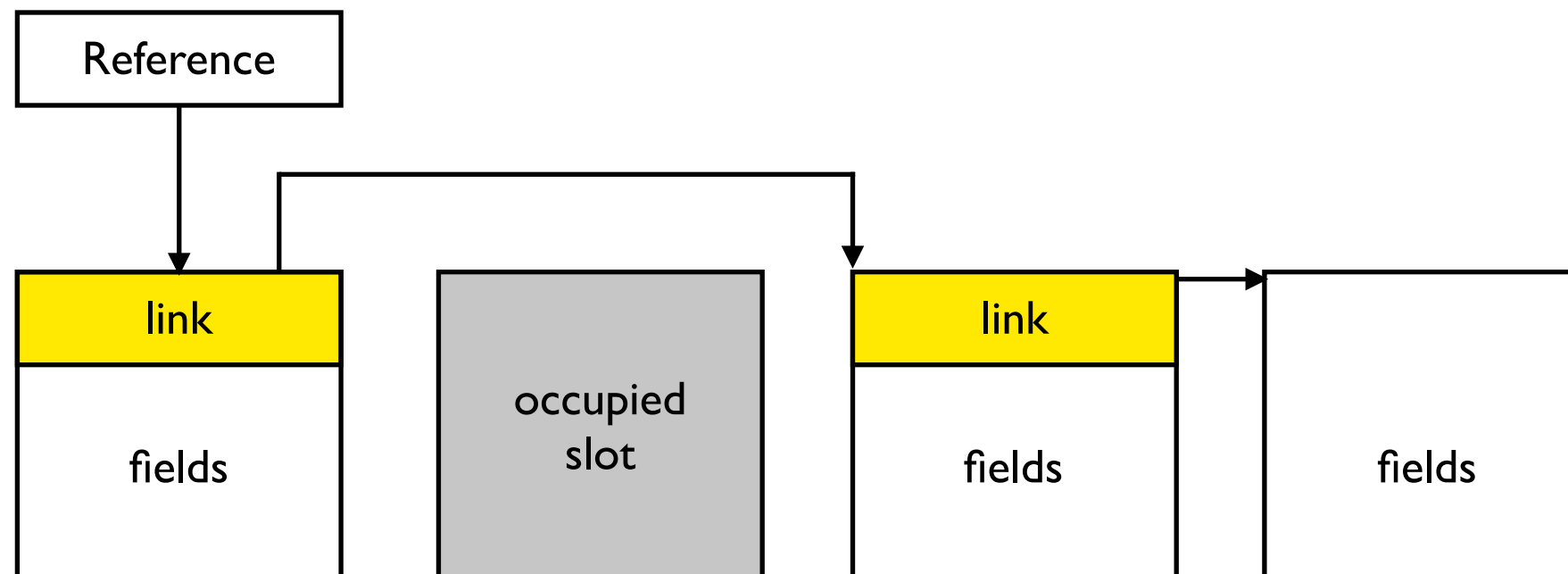
Fragmented Objects

- **Traditional heap**
 - Variable-size chunks → heap fragmentation
 - Unpredictable allocation time

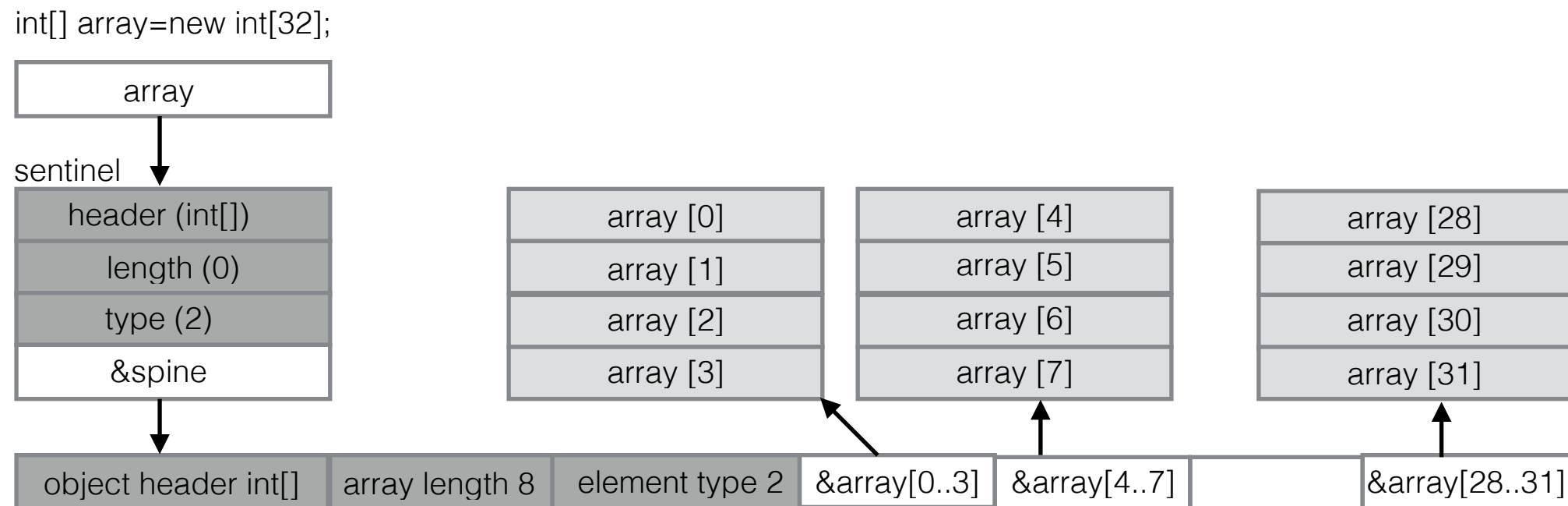


Fragmented Objects

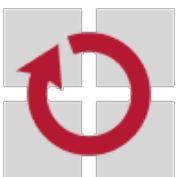
- **Traditional heap**
 - Variable-size chunks → heap fragmentation
 - Unpredictable allocation time
- **Fragmented allocation**
 - Fixed-size slots → no heap fragmentation possible
 - Fragmented objects
 - Predictable allocation time



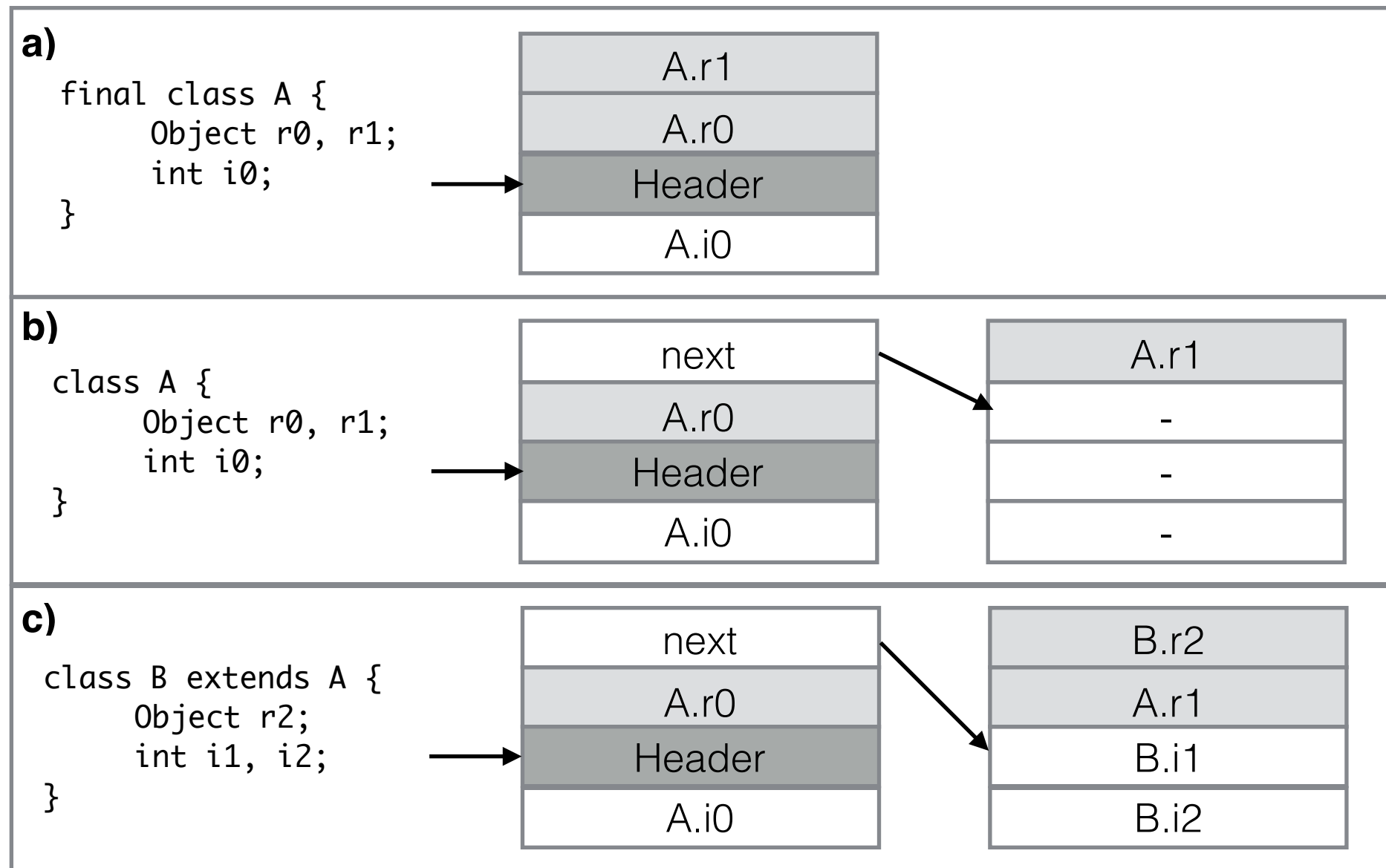
Fragmented Arrays



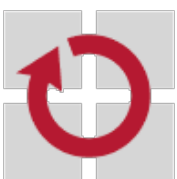
- **Spines**
 - Constant access complexity
 - Allocated in separate heap space
 - Bump pointer
 - Replicating or generational GC
- **Optimisation: omit spine if all fragments are contiguous**



Object Layout

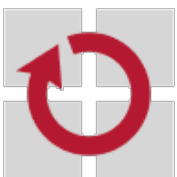


- Reference grouping for efficient scanning by GC
- ***Fragmented Bidirectional Object Layout***



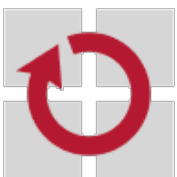
Scanning the Object Graph

- **Static references**
 - Grouped together in .data section
- **Non-static reference fields**
 - Grouped together in object fragments
- **Local references**
 - Henderson's linked stack frames
 - Only generated for blocking methods
 - Only scan stacks of currently blocked tasks



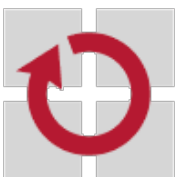
Write Barriers

- **Whenever a reference is written, mark its pointee grey**
 - Significant application overhead



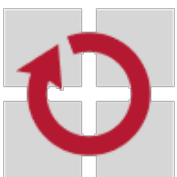
Write Barriers

- **Whenever a reference is written, mark its pointee grey**
 - Significant application overhead
- **Trade-off: latency vs. performance**
 - Omit write barriers for local references
 - During stack scanning, raise GC's priority above stack owner's
 - Short, bounded time (sans recursion)
 - GC still preemptible by higher-priority tasks
 - Also possible: omit write barriers for static fields



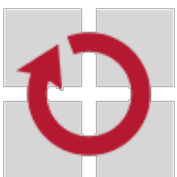
Improving GC Predictability

- **Observation: GC runtime dominated by mark phase**
 - Object-graph traversal expensive
 - Only surviving heap objects contribute
- **Survivability analysis**
 - Per-object lifespan categorisation
 - Based on escape analysis and call-graph analysis
 - Object may survive GC if reference ...
 - ... escapes globally
 - ... is live beyond blocking system calls



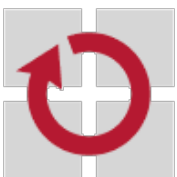
Survivability Classification

- **Method-local**
 - Automatic stack allocation



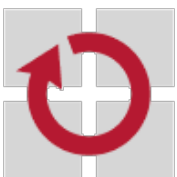
Survivability Classification

- **Method-local**
 - Automatic stack allocation
- **Region-local**
 - Automatic region-based allocation



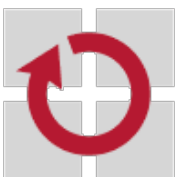
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- **Method-local**
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- **Region-local**
 - Automatic region-based allocation
- **Task-local**
 - Per-task heaps



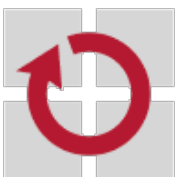
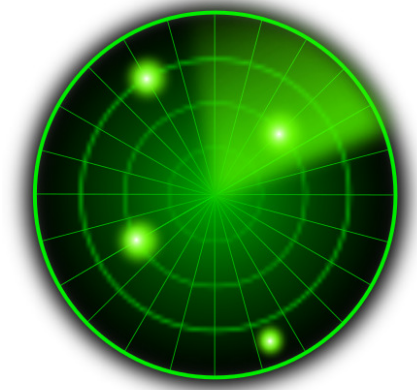
Survivability Classification

- **Method-local**
 - Automatic stack allocation
- **Region-local**
 - Automatic region-based allocation
- **Task-local**
 - Per-task heaps
- **Task-escaping**
 - Regular heap



Evaluation

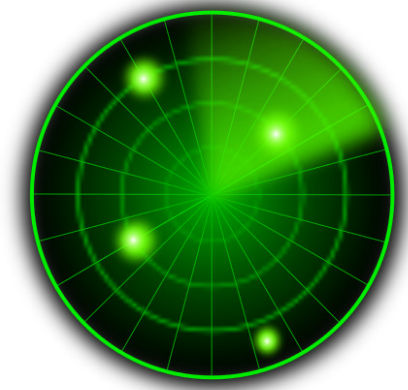
- **Collision Detector (CD_j) 1.2**
 - Real-time air-traffic simulator and collision detector
 - **CiAO** OS
 - TriCore TC1796 @ 150 MHz



Evaluation

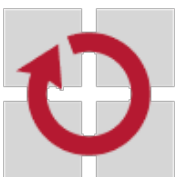
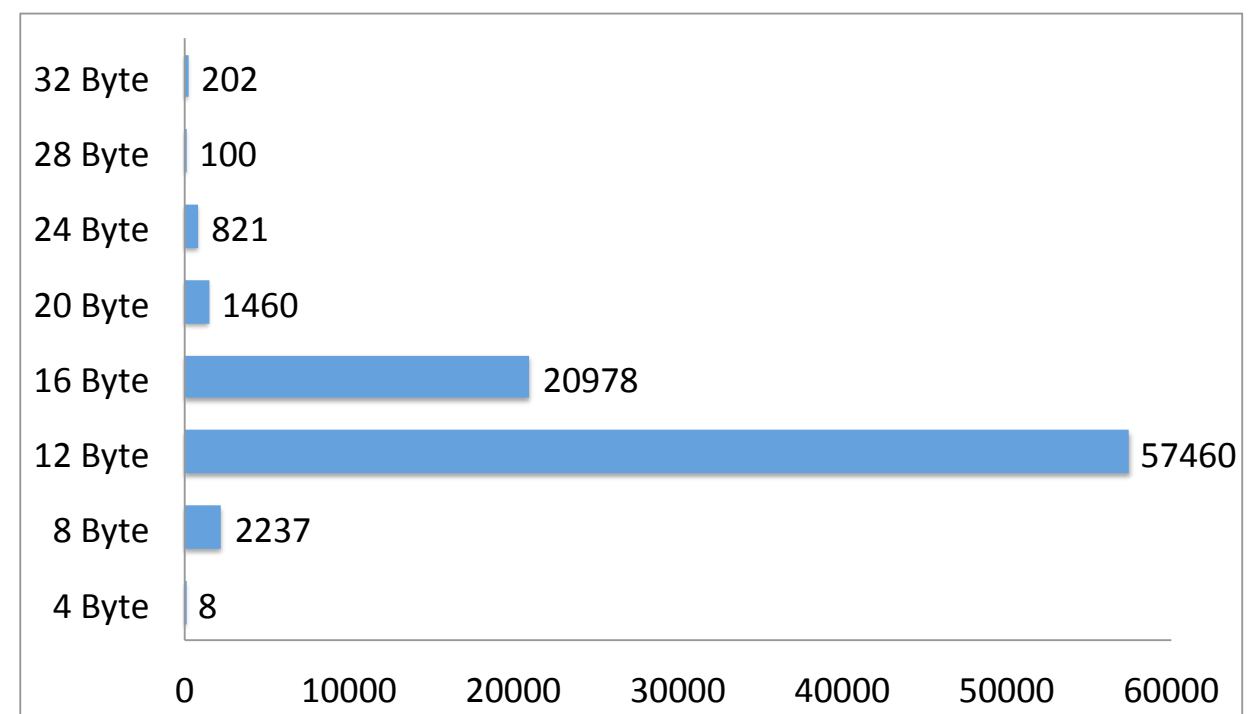
- **Collision Detector (CD_j) 1.2**

- Real-time air-traffic simulator and collision detector
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- **Object sizes**

- Regular objects are small due to by-reference semantics
- Chain length determines execution time of
 - Allocation
 - Field access



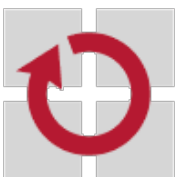
Memory Footprint / Heap Usage

- **Memory footprint**

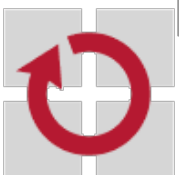
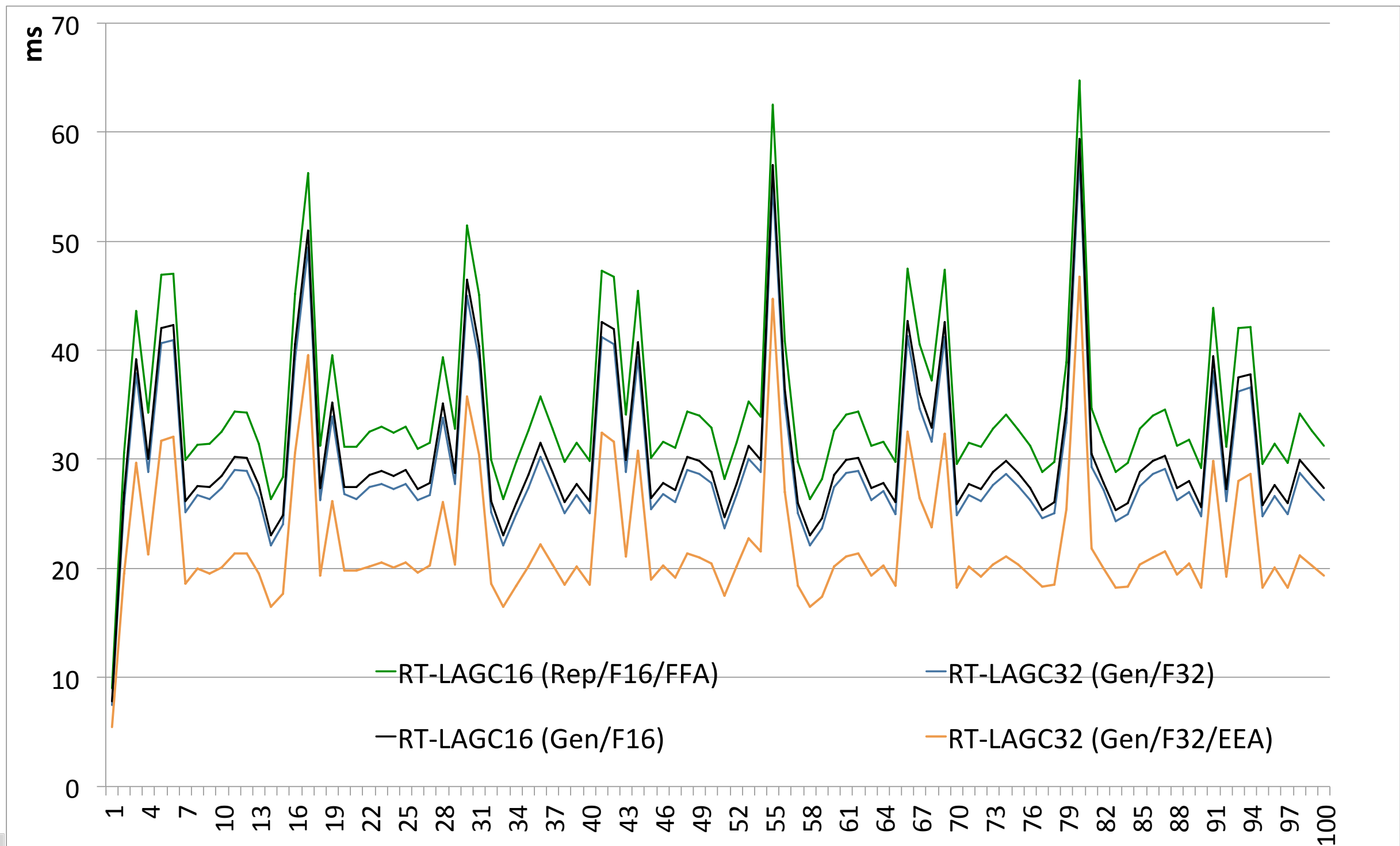
	.text	.data + .bss
Incremental	50 KiB	660 KiB
RT-LAGC	58-60 KiB	820 KiB
Δ	+ 16-20 %	+ 23 %

- **Heap usage**

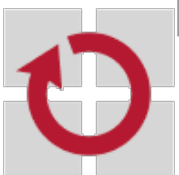
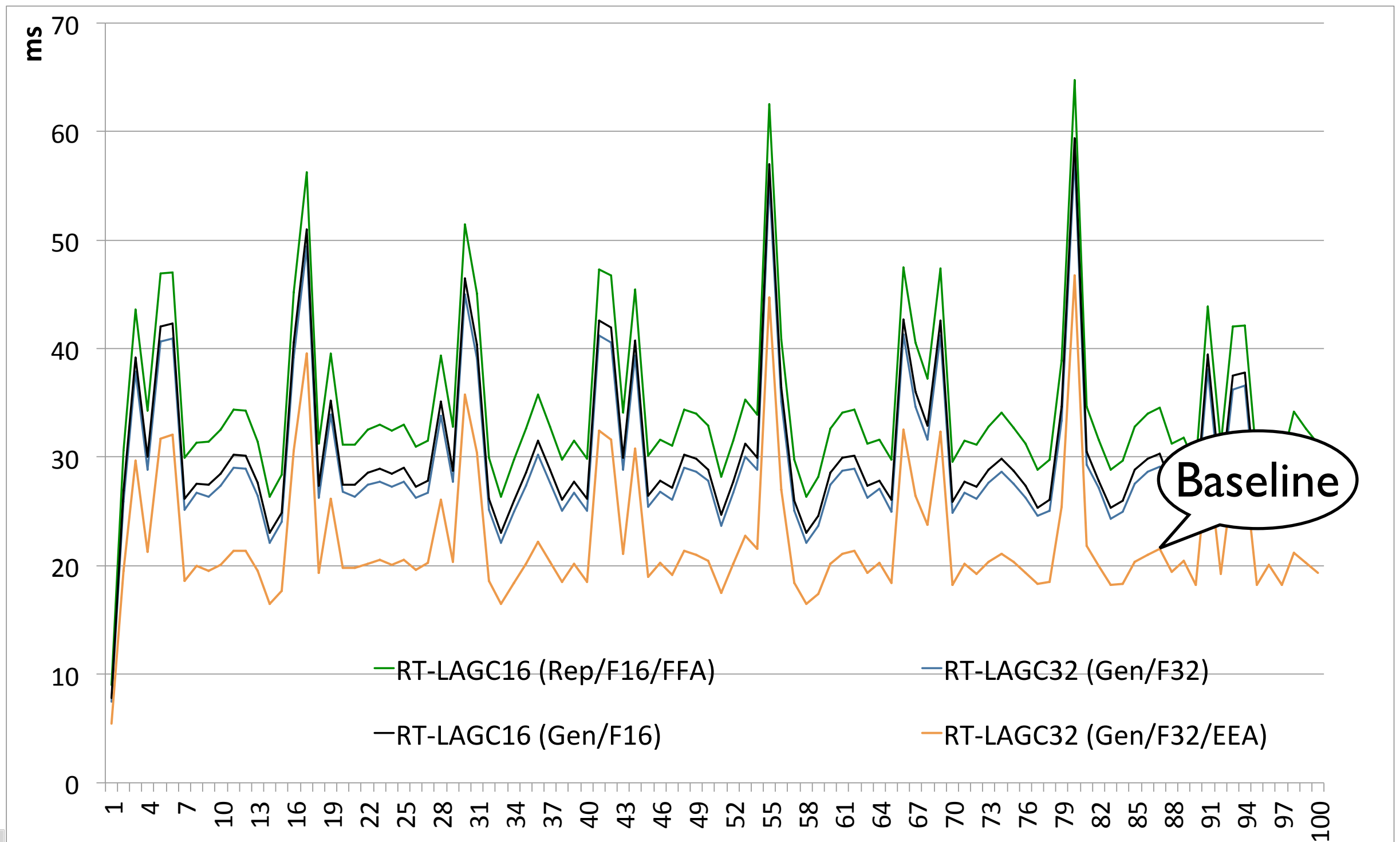
- Generational vs. replicating spines: spine memory reduced by 50 %
- Stack allocation reduces heap usage by 43 %
- 32-byte vs. 16-byte fragments: usage raised by 45 % (internal fragmentation)



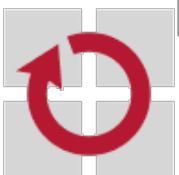
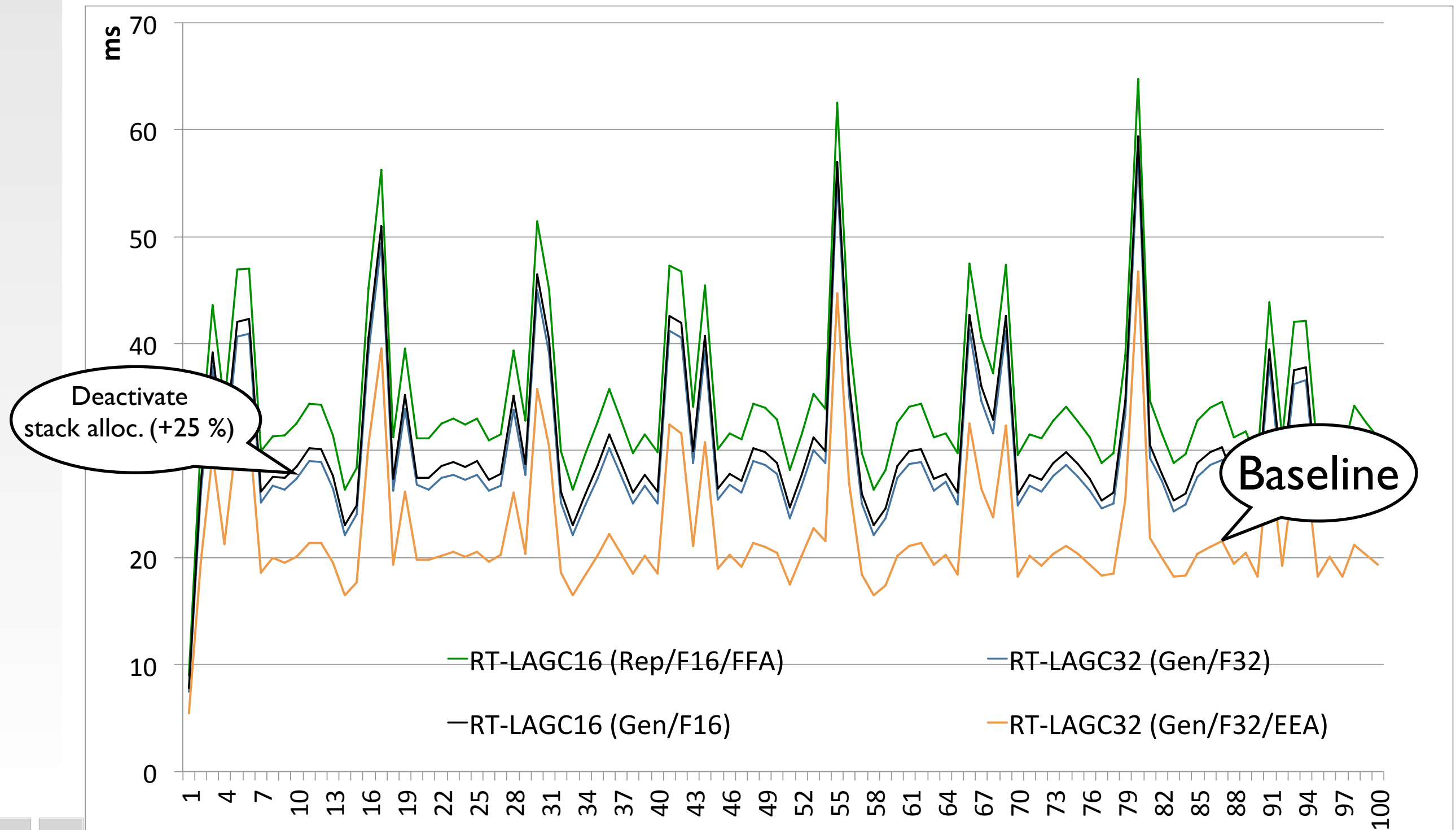
Runtime



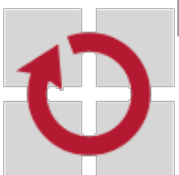
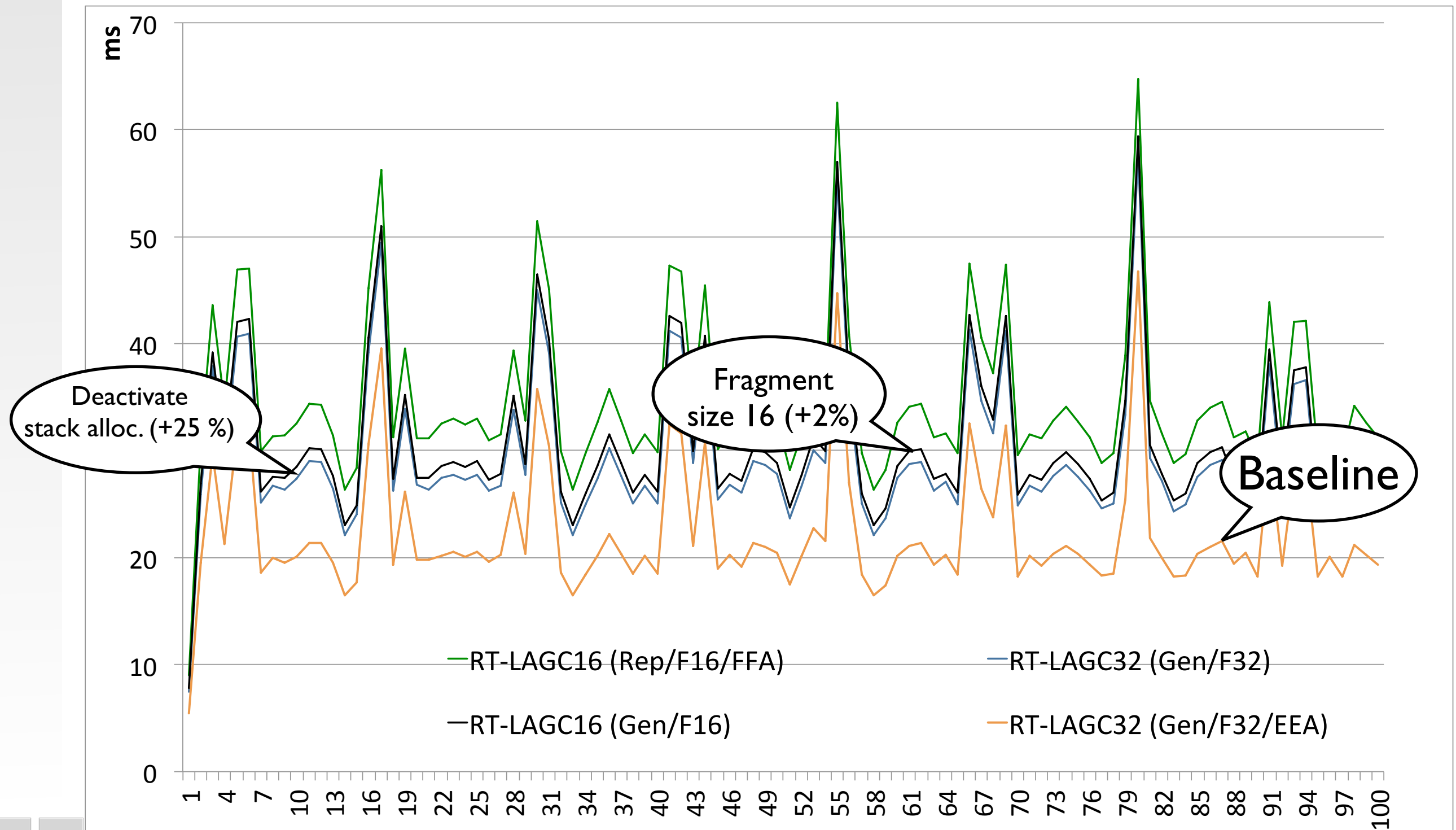
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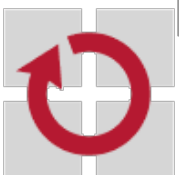
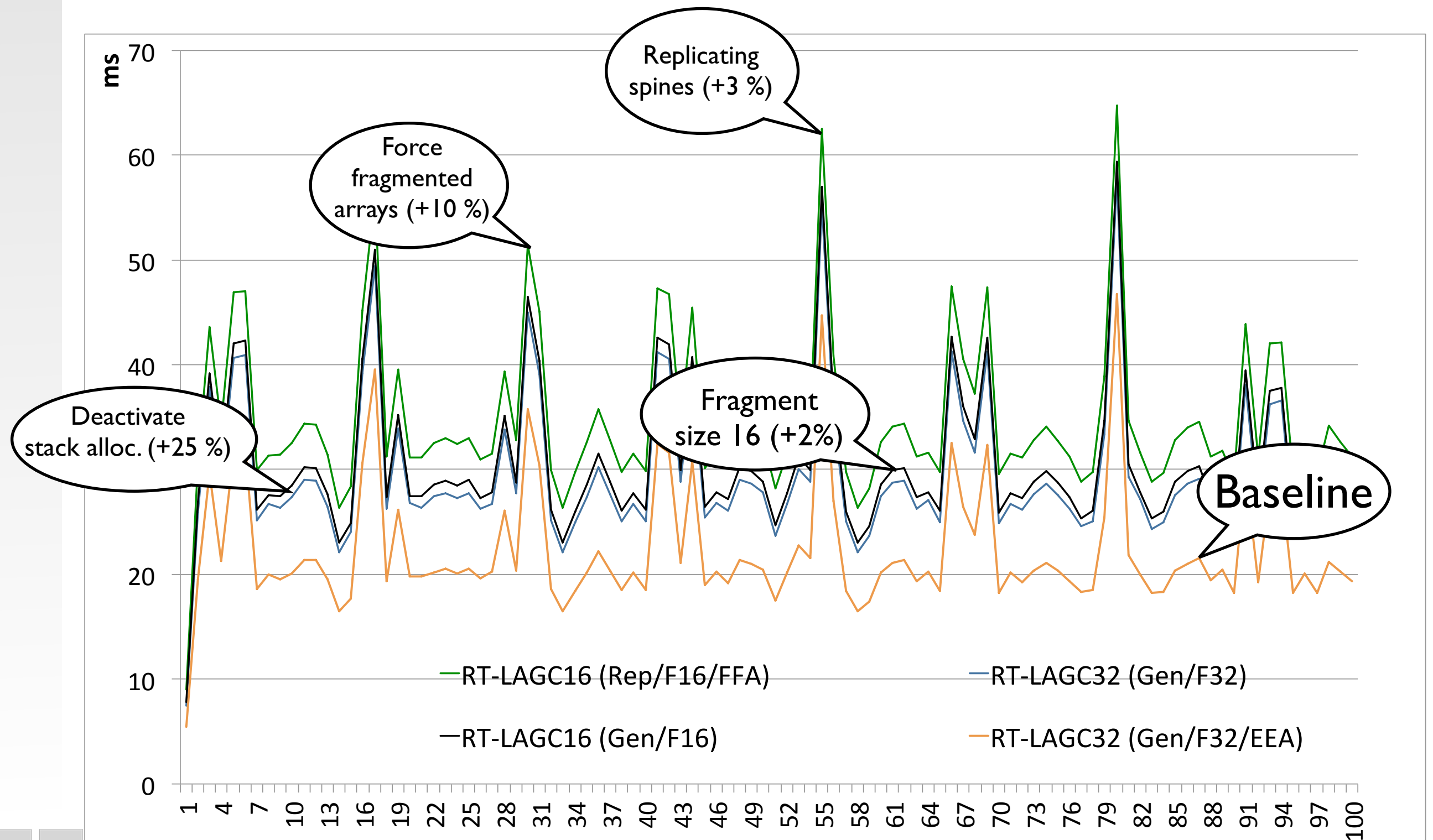
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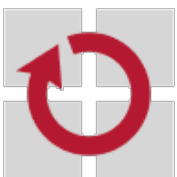
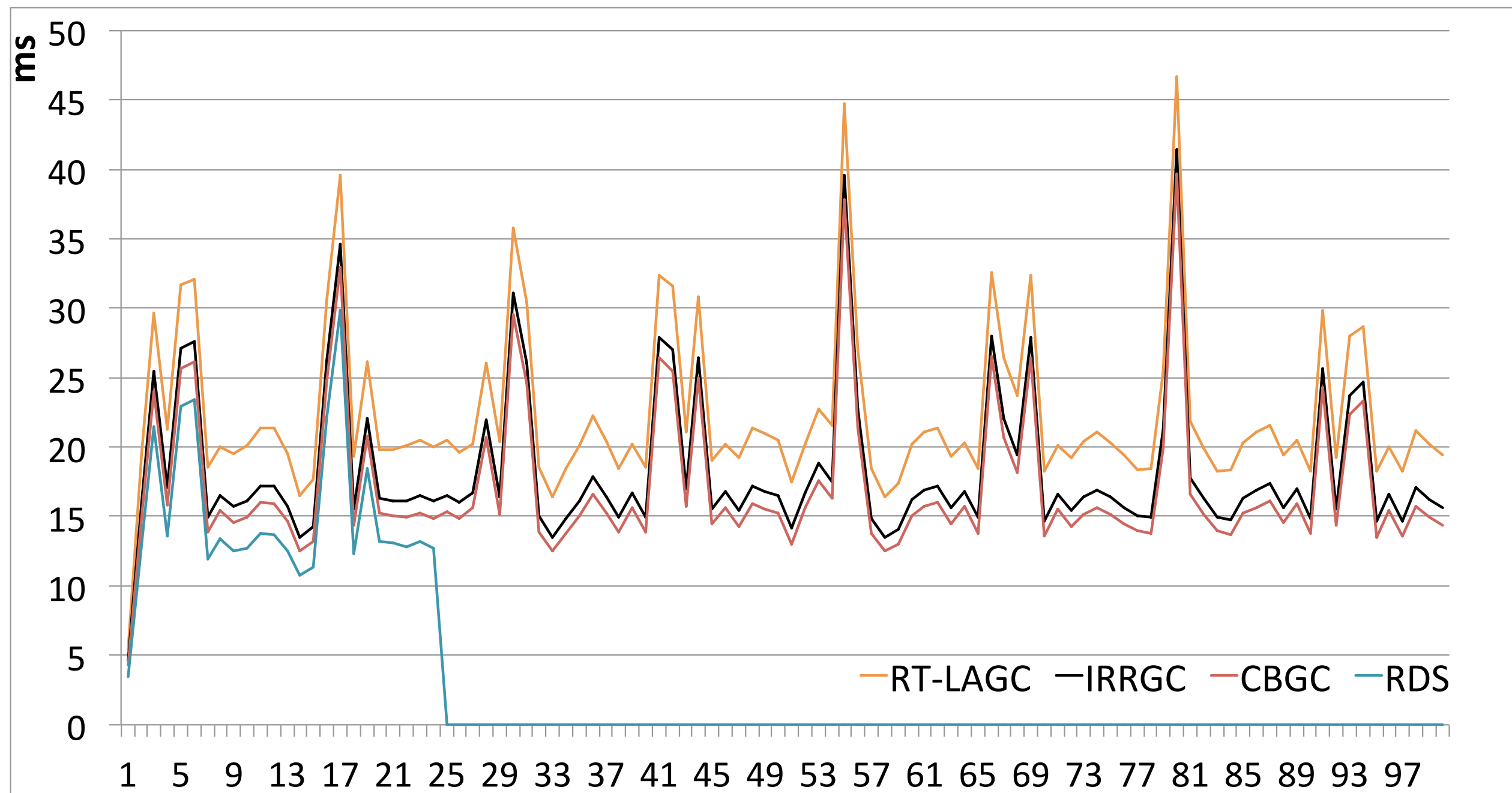
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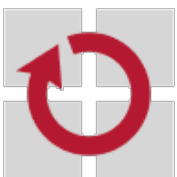
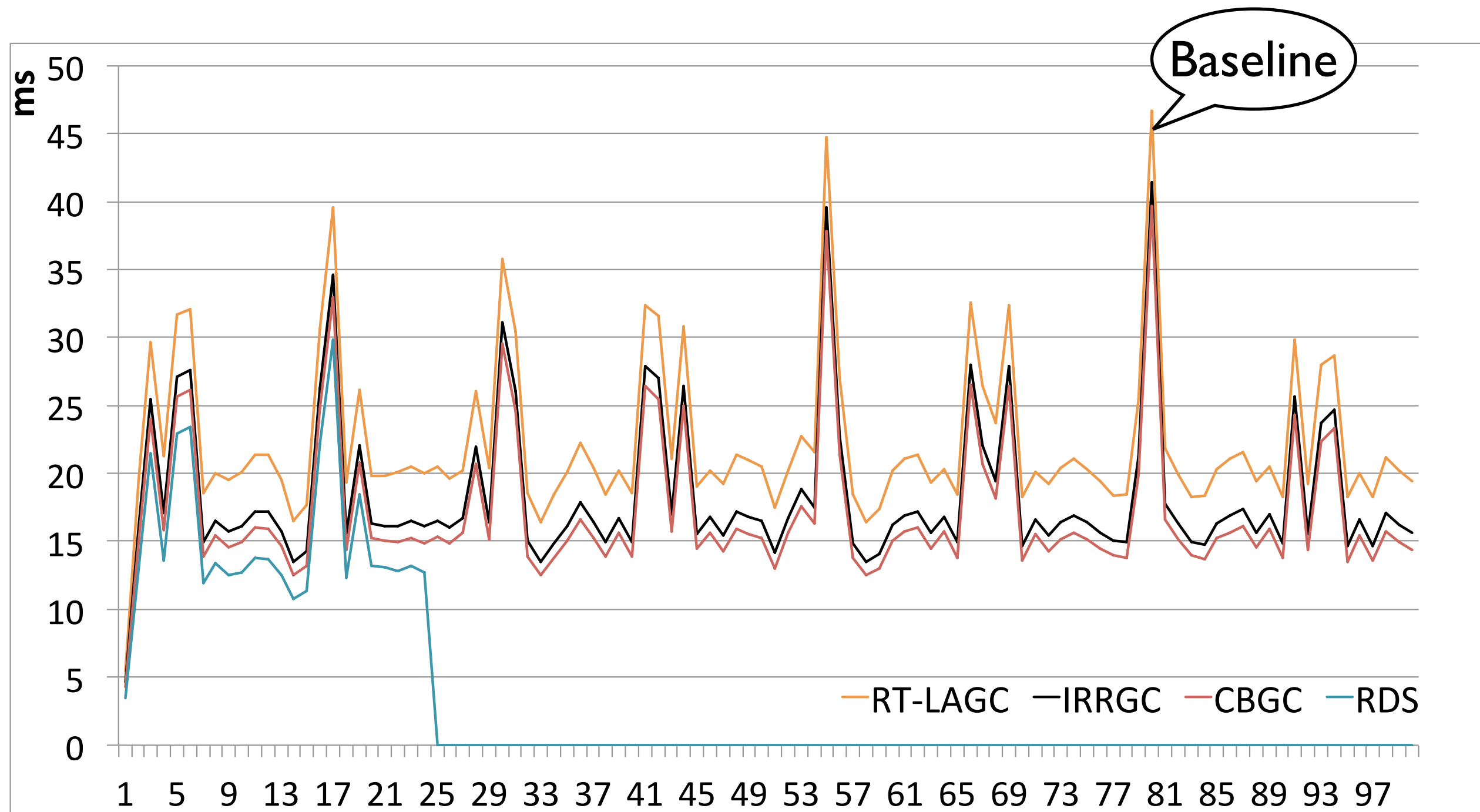
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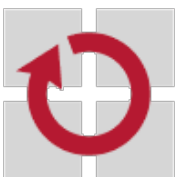
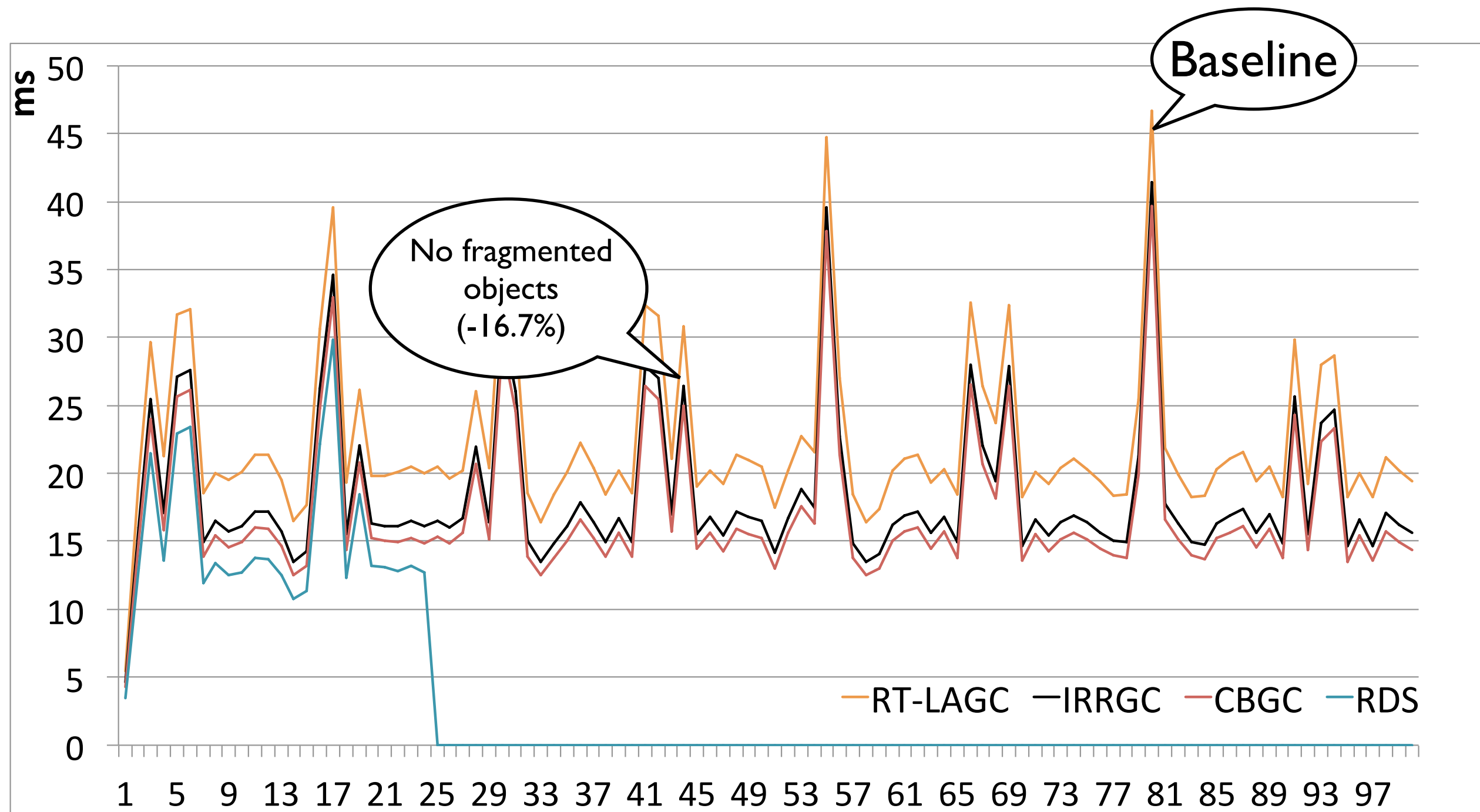
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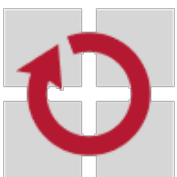
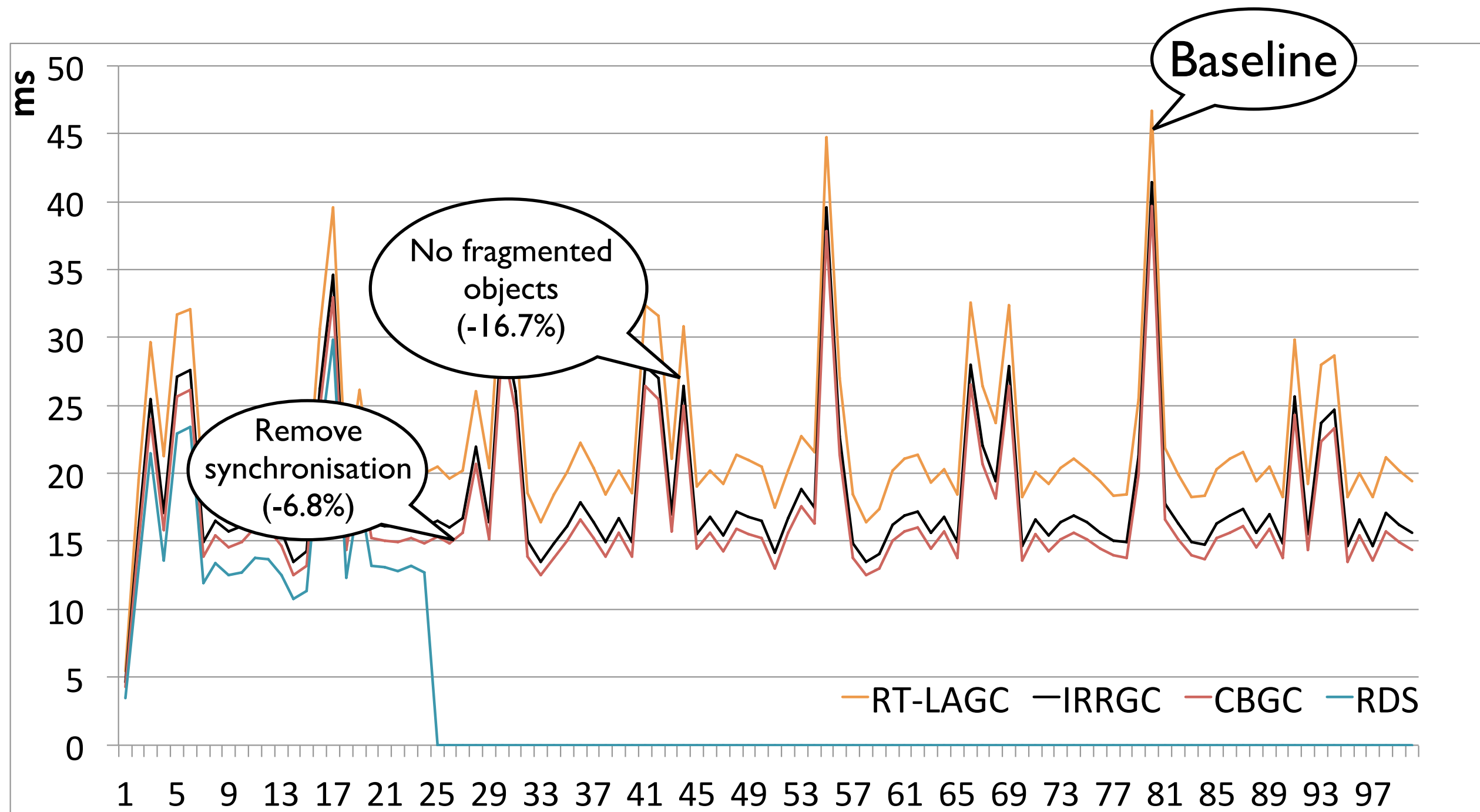
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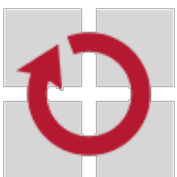
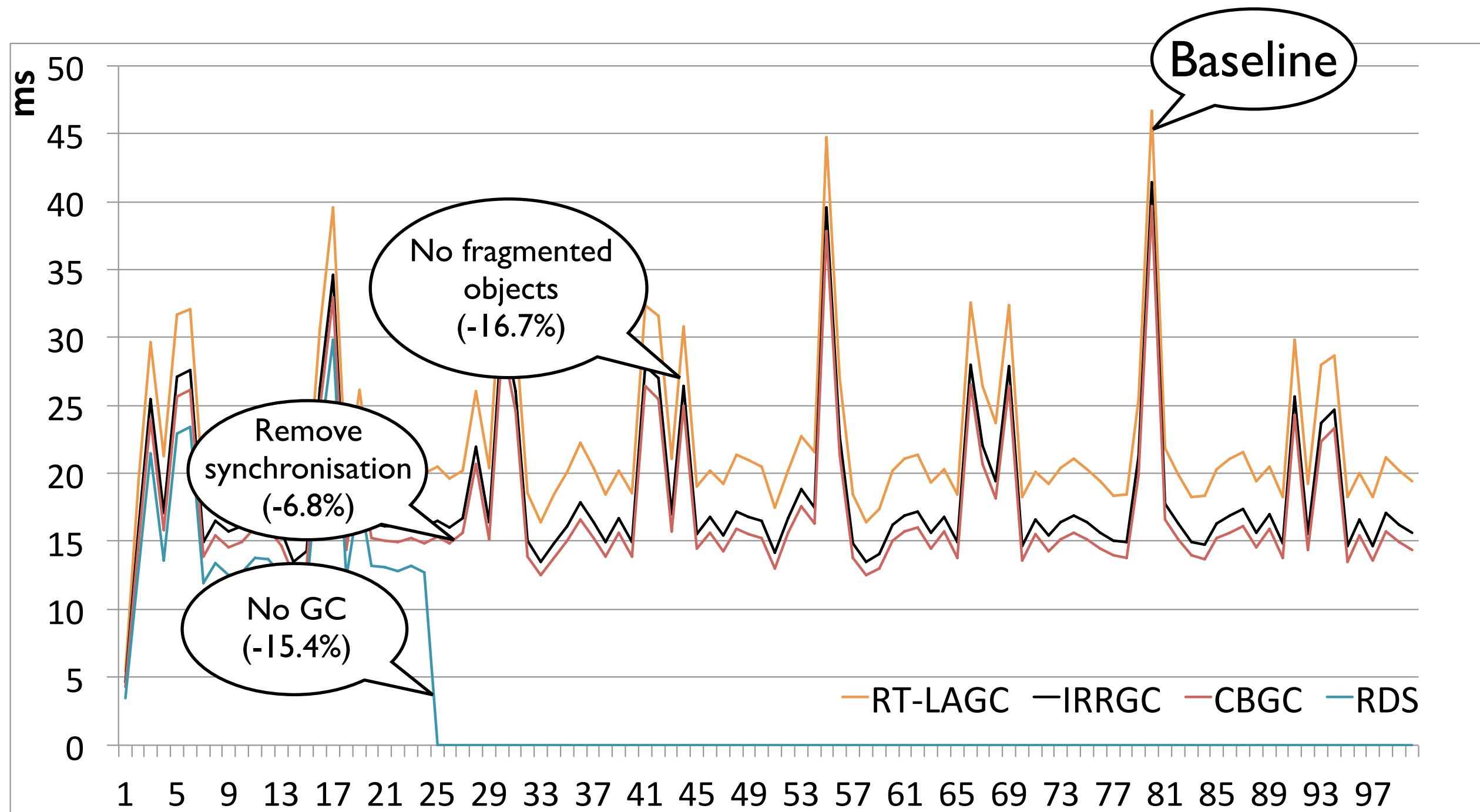
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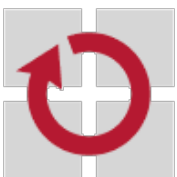
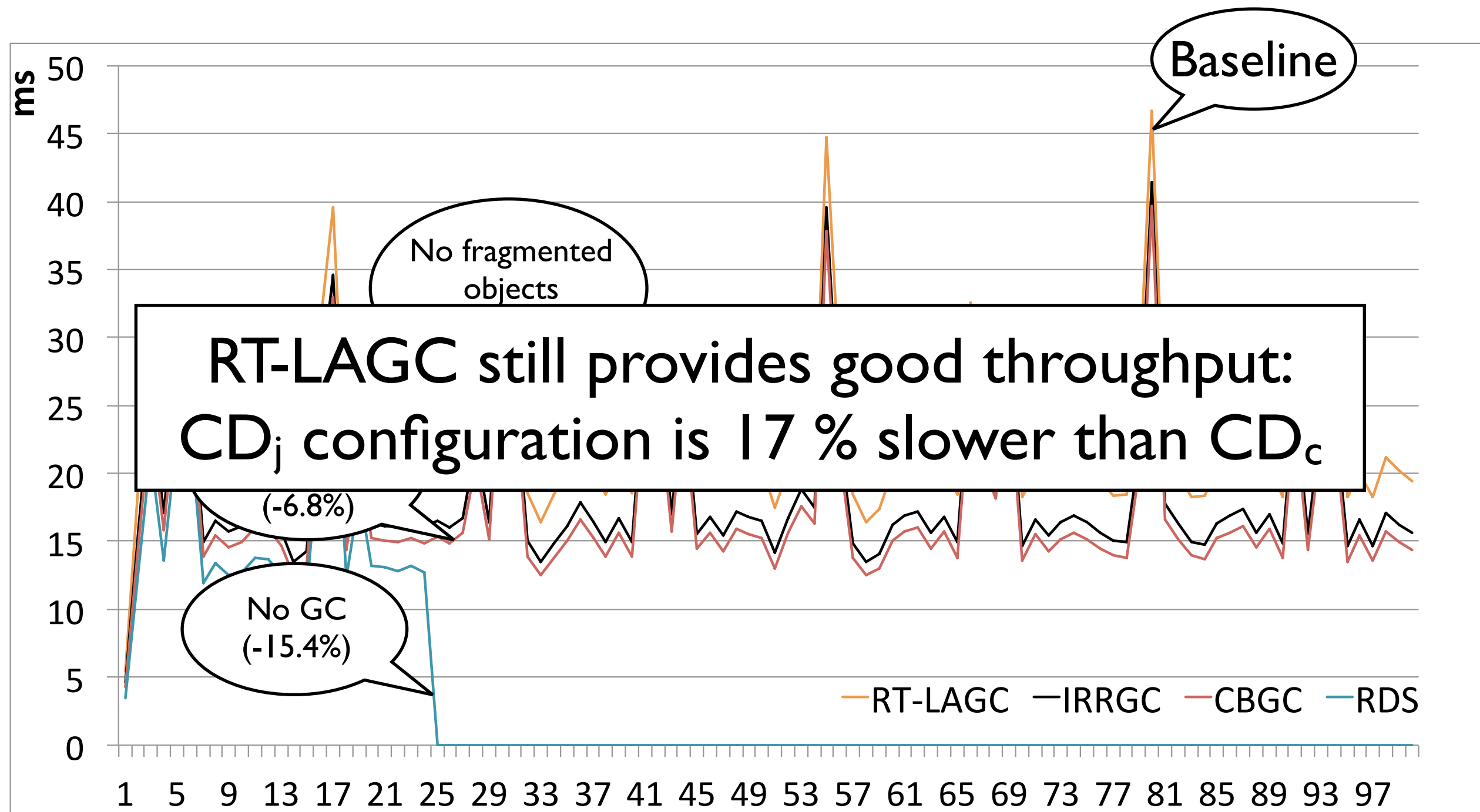
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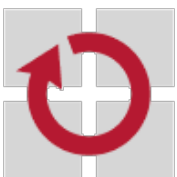


Runtime



Conclusion

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 - Cooperative approach
 - Predictable allocation times
 - Low reaction time to external events
 - Good throughput
 - Fine-grained synchronisation code



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 - Good throughput
 - Fine-grained synchronisation code
- **Developer assistance during integration**
 - Survivability analysis
 - Object sizes

