

Konfigurierbare Systemsoftware (KSS)

VL 2 – Software Product Lines

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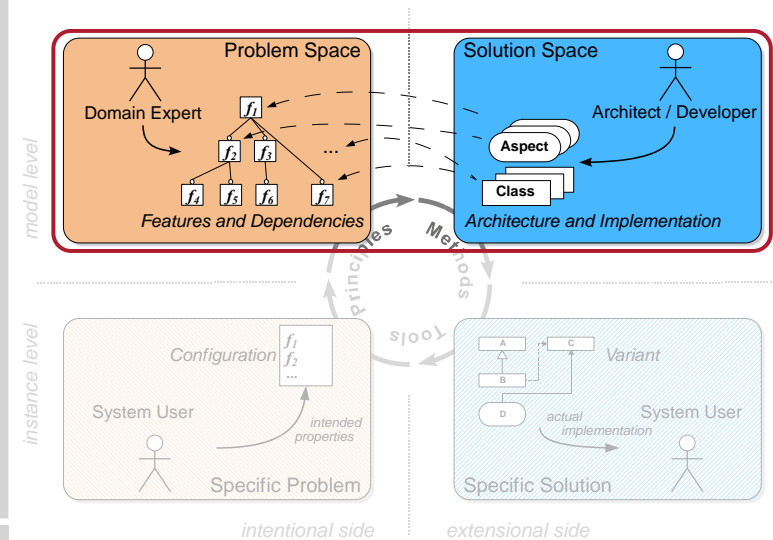
SS 13 – 2013-04-25

http://www4.informatik.uni-erlangen.de/Lehre/SS13/V_KSS

Agenda

- 2.1 Motivation: The Quest for Variety
- 2.2 Introduction: Software Product Lines
- 2.3 Case Study: i4Weathermon
- 2.4 Problem Space
- 2.5 Solution Space
- 2.6 References

About this Lecture



Agenda

- 2.1 Motivation: The Quest for Variety
 - Model Car Industry
 - Challenges
- 2.2 Introduction: Software Product Lines
- 2.3 Case Study: i4Weathermon
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- 2.5 Solution Space
- 2.6 References

Model Car Industry: Variety of an BMW X3



- Roof interior: **90000** variants available
- Car door: **3000** variants available
- Rear axle: **324** variants available

“Varianten sind ein wesentlicher Hebel für das Unternehmensergebnis”
Franz Decker (BMW Group)



optional, independent
33 features



one individual variant
for each human being

Model Car Industry: Variety Increase

■ In the 1980s: little variety

- Option to choose series and maybe a few extras (tape deck, roof rack)
- A **single variant** (Audi 80, 1.3l, 55 PS) accounted for **40 percent** of Audi's total revenue

■ Twenty years later: built-to-order

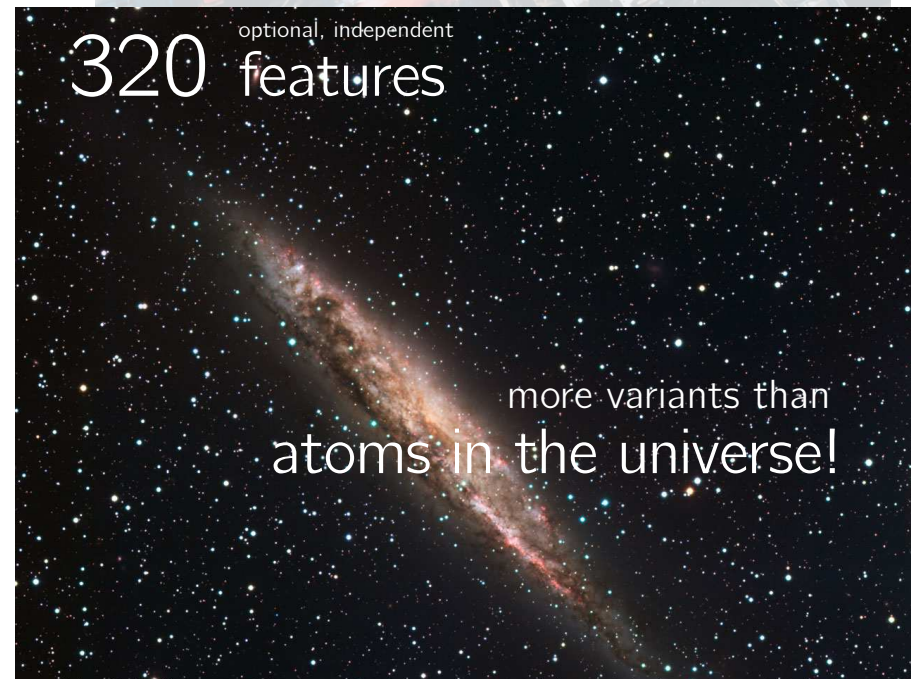
- Audi: **10^{20}** possible variants
- BMW: **10^{32}** possible variants
- At average there are 1.1 equal instances of an Audi A8 on the street

→ **Product lines** with fully automated assembly



optional, independent
320 features

more variants than
atoms in the universe!



Typical Configurable Operating Systems...

ecos

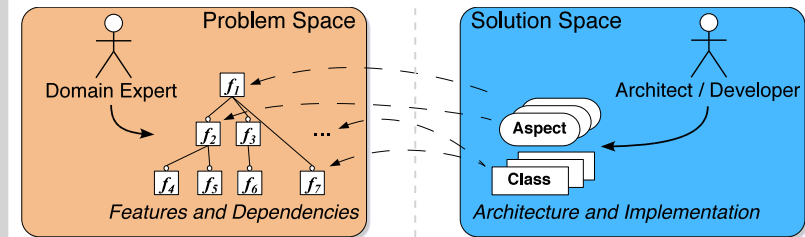
5000 features

14000 features

Agenda

- 2.1 Motivation: The Quest for Variety
- 2.2 Introduction: Software Product Lines
 - Terms and Definitions
 - SPL Development Process
 - Our Understanding of SPLs
- 2.3 Case Study: i4Weathermon
- 2.4 Problem Space
- 2.5 Solution Space
- 2.6 References

Challenges



- 1 How to **identify** the actually desired variability?
- 2 How to **express** the intended variability?
- 3 How to **implement** this variability in the code?
- 4 How to **map** variability options to the code?

Definition: (Software) Product Line, Feature

Product Line (Withey) (Definition 1)

“ A **product line** is a group of products sharing a common, managed set of **features** that satisfy the specific needs of a selected **market**. ”

Withey 1996: *Investment Analysis of Software Assets for Product Lines* [12]

Software Product Line (SEI) (Definition 2)

“ A **software product line (SPL)** is a set of software-intensive systems that share a common, managed set of **features** satisfying the specific needs of a particular **market** segment or mission and that are developed from a common set of core assets in a prescribed way. ”

Northrop and Clements 2001: *Software Product Lines: Practices and Patterns* [8]

Remarkable:

SPLs are not motivated by **technical** similarity of the products, but by **feature** similarity wrt a certain **market**

Definition: (Software) Product Line, Feature

Product Line (Withey)

(Definition 1)

“ A **product line** is a group of products sharing a common, managed set of **features** that satisfy the specific needs of a selected **market**. ”

Withey 1996: *Investment Analysis of Software Assets for Product Lines* [12]

Software Product Line (SEI)

(Definition 2)

“ A **software product line (SPL)** is a set of software-intensive systems that share a common, managed set of **features** satisfying the specific needs of a particular **market segment** or mission and that are developed from a common set of core assets in a prescribed way. ”

Northrop and Clements 2001: *Software Product Lines: Practices and Patterns* [8]

Feature (Czarnecki / Eisenecker)

(Definition 3)

“ A distinguishable characteristic of a concept [...] that is relevant to some stakeholder of the concept. ”

Czarnecki and Eisenecker 2000: *Generative Programming. Methods, Tools and Applications* [3, p. 38]



The Emperors New Clothes?

Program Family

(Definition 4)

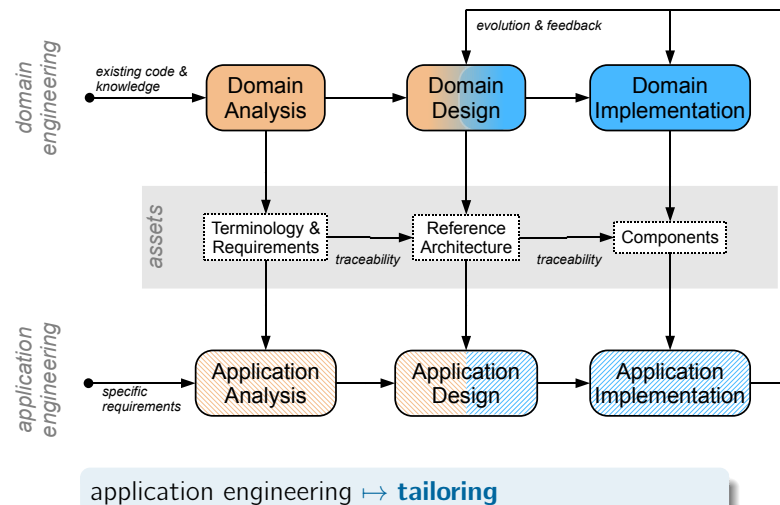
“ Program families are defined [...] as sets of programs whose common properties are so extensive that it is advantageous to study the common properties of the programs before analyzing individual members. ”

Parnas 1976: “On the Design and Development of Program Families” [10]

- Most research on operating-system *families* from the '70s would today qualify as work on software product lines [2, 4, 5, 9–11]
 - Program Family \Leftrightarrow Software Product Line
- However, according to the definitions, the viewpoint is different
 - Program family: defined by similarity between **programs** \rightarrow **Solutions**
 - SPL: defined by similarity between **requirements** \rightarrow **Problems**
- \Rightarrow A program family **implements** a software product line
- In current literature, however, both terms are used synonymously
 - Program Family \Leftrightarrow Software Product Line



SPL Development Reference Process [1]



Our understanding: Configurable System Software

Configurability

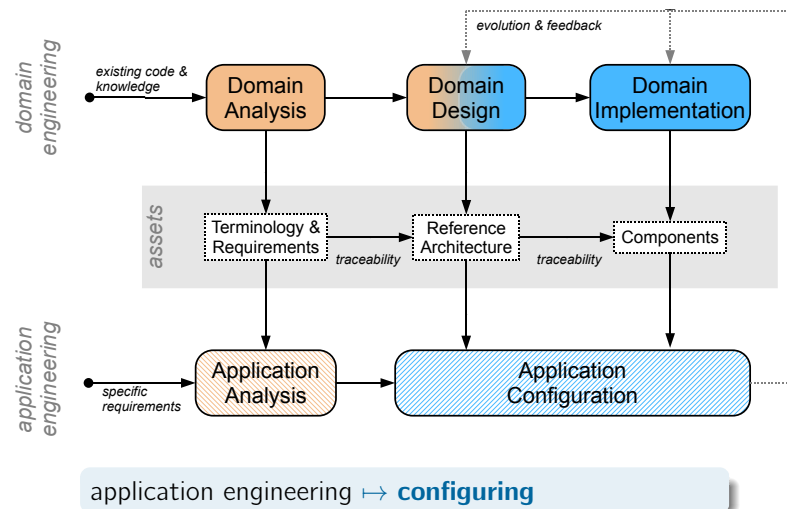
(Definition 5)

Configurability is the property that denotes the degree of pre-defined variability and granularity offered by a piece of system software via an explicit **configuration interface**.

- Common configuration interfaces
 - Text-based: **configure** script or **configure.h** file (GNU tools)
 - configuration by commenting/uncommenting of (preprocessor) flags
 - no validation, no explicit notion of feature dependencies
 - Tool-based: KConfig (Linux, busybox, CiAO, ...), ecosConfig (eCos)
 - configuration by an interactive configuration editor
 - formal model of configuration space, hierarchical features
 - implicit/explicit validation of constraints



Configurable SPL Reference Process



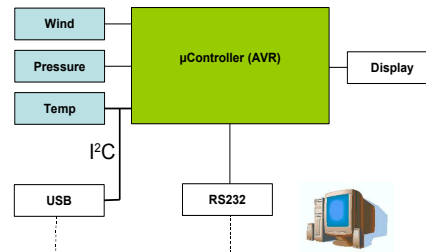
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The i4WeatherMon Weather Station

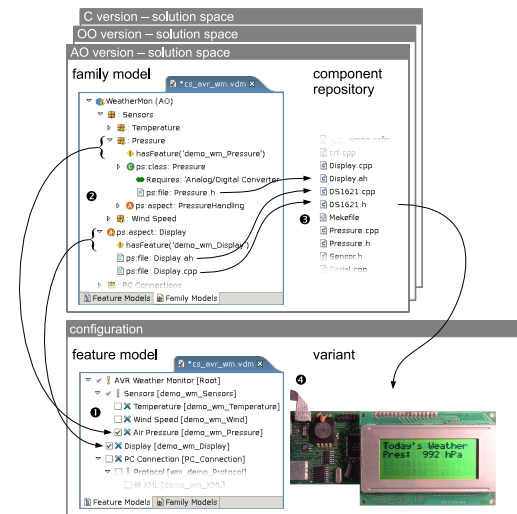
[7]

- A typical embedded system
 - Several, optional **sensors**
 - Wind
 - Air Pressure
 - Temperature
 - Several, optional **actuators** (here: output devices)
 - LCD
 - PC via RS232
 - PC via USB
- To be implemented as a product line
 - **Barometer**: Pressure + Display
 - **Thermometer**: Temperature + Display
 - **Deluxe**: Temperature + Pressure + Display + PC-Connection
 - **Outdoor**: <as above> + Wind
 - ...



The i4WeatherMon Software Product Line

[7]

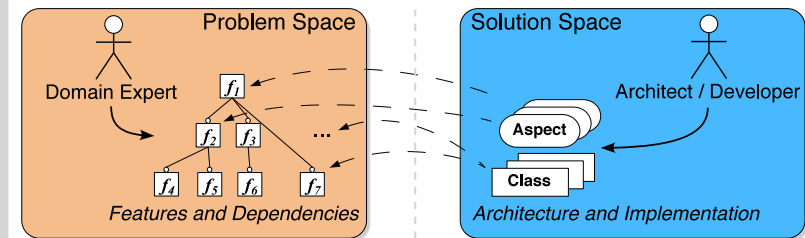


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- 2.4 Problem Space
 - Domain Analysis
 - Feature Modelling
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- 2.6 References



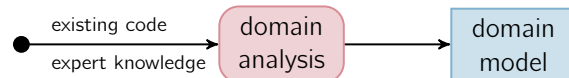
Challenges



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Domain Analysis



- **Domain Scoping**
 - Selection and processing of domain knowledge
 - Restriction of diversity and variety
- **Domain Modelling**
 - Systematic evaluation of the gained knowledge
 - Development of a taxonomy

~ **Domain Model** (Definition 6)

“ A **domain model** is an explicit representation of the **common** and the **variable** properties of the system in a domain, the semantics of the properties and domain concepts, and the dependencies between the variable properties. ”

Czarnecki and Eisenecker 2000: *Generative Programming. Methods, Tools and Applications* [3]



Elements of the Domain Model

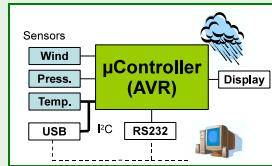
- **Domain definition** specifies the scope of the domain
 - Examples and counter examples
 - Rules for inclusion/exclusion of systems or features
- **Domain glossary** defines the vocabulary of the domain
 - Naming of features and concepts
- **Concept models** describe relevant concepts of the domain
 - Formal description (e.g., by UML diagrams)
 - Textual description
 - Syntax and semantics
- **Feature models** describe the common and variable properties of domain members
 - Textual description
 - Feature diagrams



I4WeatherMon: Domain Model (simplified)

Domain Definition: i4WeatherMon

- The domain contains software for the depicted modular hardware platform. Future version should also support new sensor and actuator types (humidity, alarm, ...).
- The externally described application scenarios **thermometer**, **PC**, **outdoor**, ... shall be supported.
- The i4WeatherMon controller software is shipped in the flash memory of the μ C and shall not be changed after delivery.
- The i4WeatherMon shall be usable with all versions of the **PC Weather** client software.
- ...



I4WeatherMon: Domain Model (simplified)

Domain Glossary: i4WeatherMon

- **PC Connection:** Optional communication channel to an external PC for the sake of continuous transmission of weather data. Internally also used for debug purposes.
- **Sensor:** Part (1 or more) of the i4WeatherMon hardware that measures a particular weather parameter (such as: temperature or air pressure).
- **Actuator:** Part (1 or more) of the i4WeatherMon hardware that processes weather data (such as: LCD).
- **XML Protocol:** XML-based data scheme for the transmission of arbitrary weather data over a **PC Connection**.
- **SNG Protocol:** Binary legacy data scheme for the transmission of wind, temperature and air pressure data only over a **PC Connection**. The data scheme is used by versions < 2.0 of **PC Weather**.
- ...



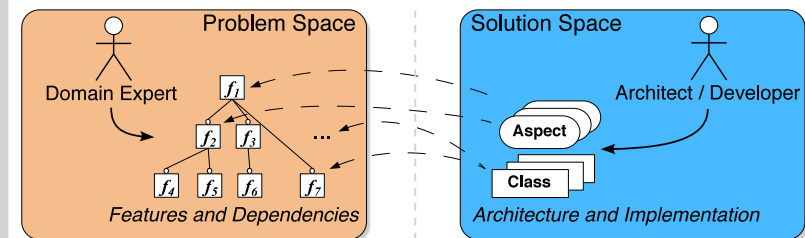
I4WeatherMon: Domain Model (simplified)

Concept Models: i4WeatherMon

- **XML Protocol:** The following DTD specifies the format used for data transmission over a **PC Connection**:
`<!ELEMENT weather ...> ...`
- **SNG Protocol:** Wind, temperature and air pressure data are encoded into 4 bytes, sequentially transmitted as a 3-byte datagram over a **PC Connection** as follows:
`...`
- **PC Connection** ...
- ...



Challenges

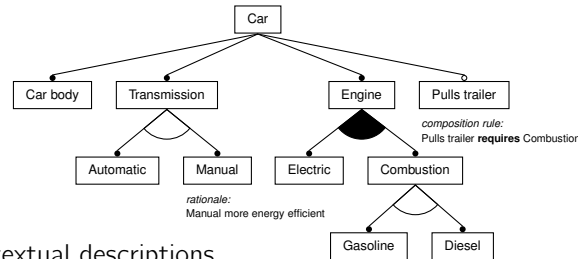


- 1 How to **identify** the actually desired variability?
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Feature Models

- Describe system variants by their commonalities and differences
 - Specify configurability in terms of optional and mandatory features
 - Intentional construct, independent from actual implementation
- Primary element is the **Feature Diagram**:
 - Concept (Root)
 - Features
 - Constraints



- Complemented by textual descriptions
 - Definition and rationale of each feature
 - Additional constraints, binding times, ...



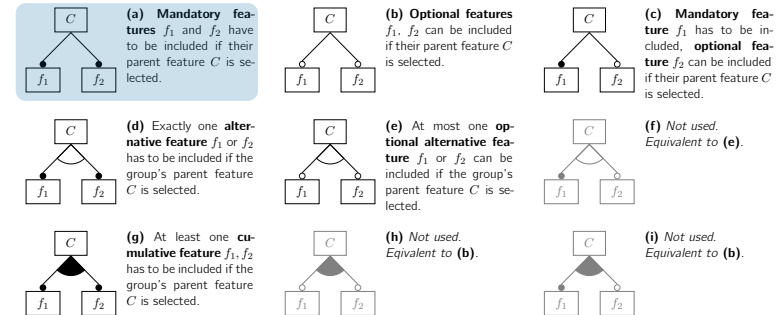
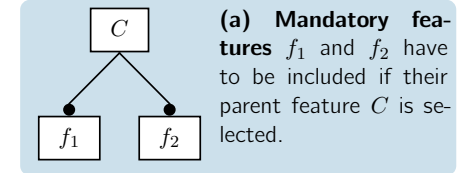
Feature Diagrams – Language

[3]

Syntactical Elements

The filled dot • indicates a mandatory feature:

$$\mathcal{V} = \{(C, f_1, f_2)\}$$



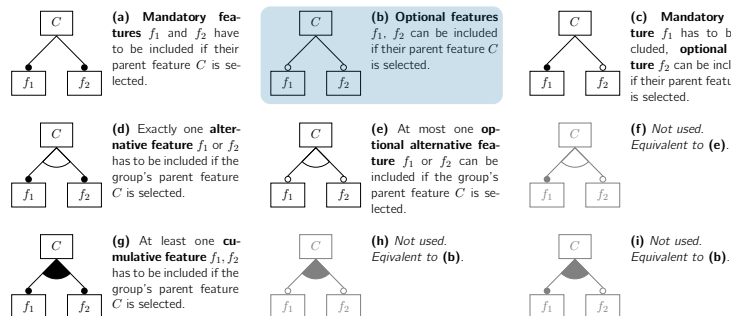
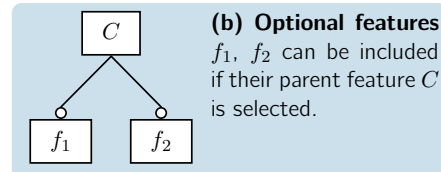
Feature Diagrams – Language

[3]

Syntactical Elements

A shallow dot ◦ indicates an optional feature:

$$\mathcal{V} = \{(C), (C, f_1), (C, f_2), (C, f_1, f_2)\}$$



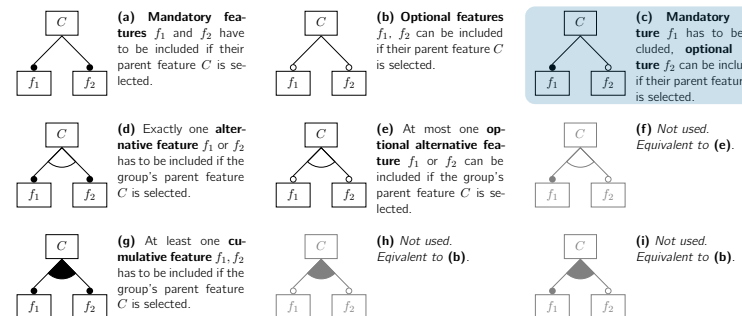
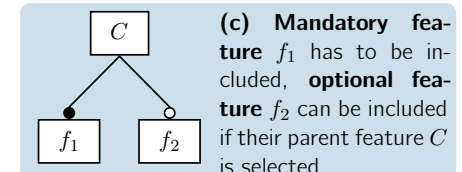
Feature Diagrams – Language

[3]

Syntactical Elements

Of course, both can be combined:

$$\mathcal{V} = \{(C, f_1), (C, f_1, f_2)\}$$



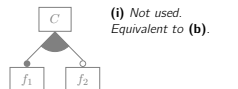
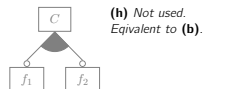
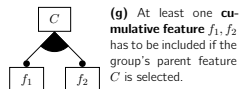
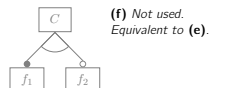
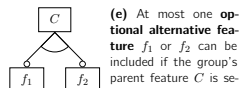
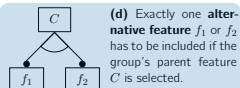
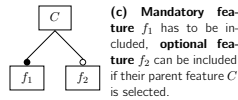
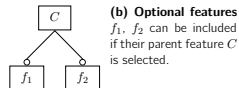
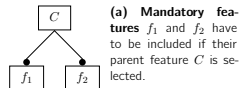
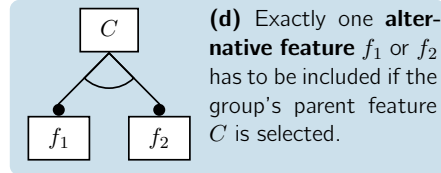
Feature Diagrams – Language

[3]

Syntactical Elements

The shallow arc \triangle depicts a group of alternative features:

$$\mathcal{V} = \{(C, f_1), (C, f_2)\}$$



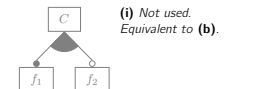
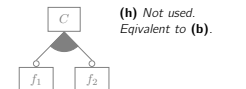
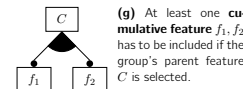
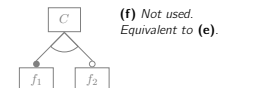
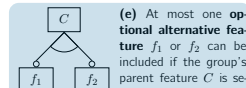
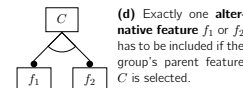
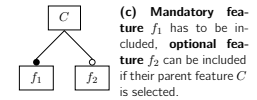
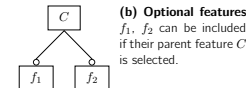
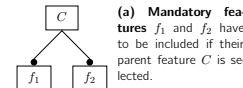
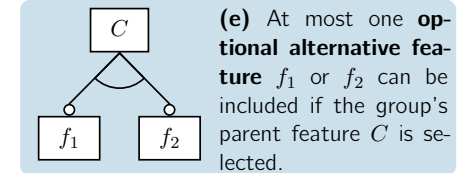
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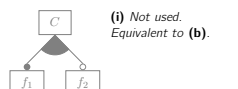
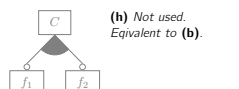
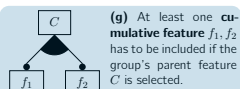
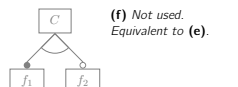
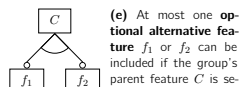
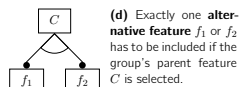
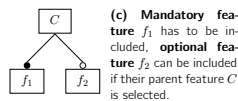
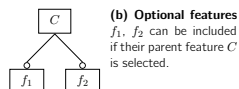
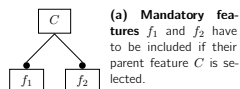
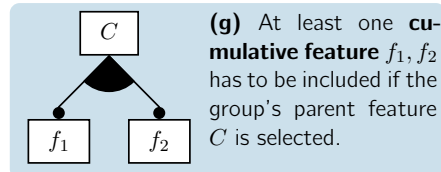


Feature Diagrams – Language

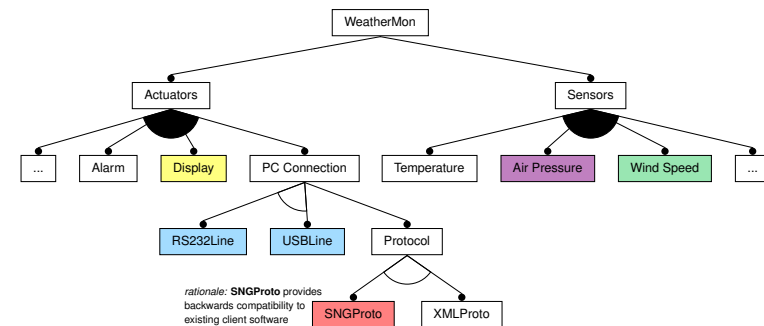
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Syntactical Elements

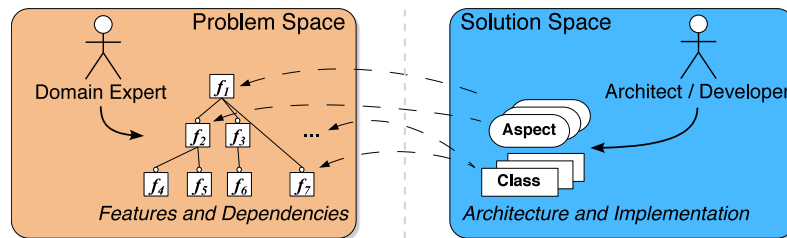
The filled arc \blacktriangle depicts a group of cumulative features: $\mathcal{V} = \{(C, f_1), (C, f_2), (C, f_1, f_2)\}$



I4WeatherMon: Feature Model



Challenges



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- 2.2 Introduction: Software Product Lines
- 2.3 Case Study: i4Weathermon
- 2.4 Problem Space
- 2.5 Solution Space
 - Reference Architecture
 - Implementation Techniques Overview
 - Variability Implementation with the C Preprocessor
 - Variability Implementation with OOP (C++)
 - Evaluation and Outlook
- 2.6 References



i4WeatherMon: Reference Architecture

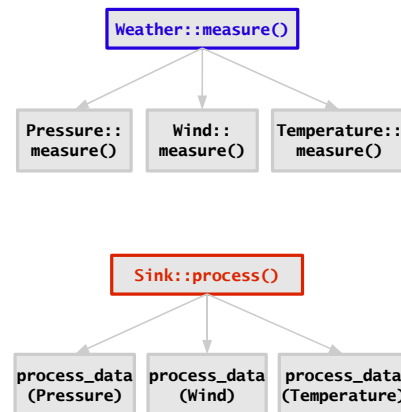
Functional decomposition (structure and process):

```
int main() {
    Weather data;
    Sink sink;

    while(true) {
        // aquire data
        data.measure();

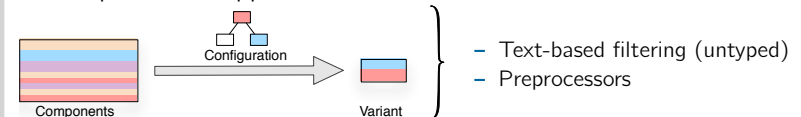
        // process data
        sink.process( data );

        wait();
    }
}
```

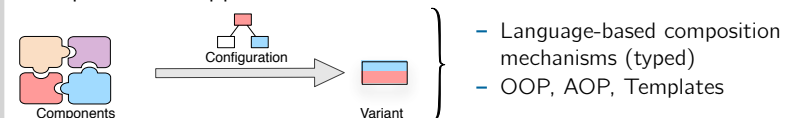


Implementation Techniques: Classification

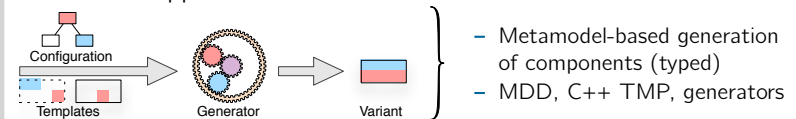
Decompositional Approaches



Compositional Approaches



Generative Approaches



Implementation Techniques: Goals

General

- ① Separation of concerns (SoC)
- ② Resource thriftiness

Operational

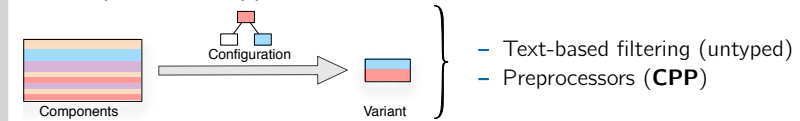
- ③ **Granularity** Components should be fine-grained. Each artifact should either be mandatory or dedicated to a single feature only.
- ④ **Economy** The use of memory/run-time expensive language features should be avoided as far as possible. Decide and bind as much as possible at generation time.
- ⑤ **Pluggability** Changing the set of optional features should not require modifications in any other part of the implementation. Feature implements should be able to “integrate themselves”.
- ⑥ **Extensibility** The same should hold for new optional features, which may be available in a future version of the product line.

I4WeatherMon (CPP): Implementation (Excerpt)

[illegible]

Implementation Techniques: The C Preprocessor

- Decompositional Approaches



- Conditional compilation with the C Preprocessor (CPP) is *the* standard approach to implement static configurability [6]
 - Simplicity: the CPP “is just there”
 - Economy: CPP-usage does not involve any run-time overhead
 - Prominent especially in the domain of system software (Linux 3.2: **85000** `#ifdef` Blocks → **“`#ifdef` hell”**)

I4WeatherMon (CPP): Implementation (Excerpt)

[illegible]

Sensor integration cross-cuts the central data structure, an interaction with a mandatory feature.

I4WeatherMon (CPP): Implementation (Excerpt)

[illegible]

Sensor (and actuator) integration both crosscut the structure of the main program, an interaction with a mandatory feature.

I4WeatherMon (CPP): Implementation (Excerpt)

```
inline void XMLCon::process() {
    char val[ 5 ];

    Serial::send ("<?xml version=\"1.0\"?>\n" "<weather>\n");

    #ifdef cFWM_WIND
        wind_stringval( val );
        XMLCon.data ( wind_name(), val );
    #endif

    #ifdef cFWM_PRESSURE
        pressure_stringval( val );
        XMLCon.data ( pressure_name(), val );
    #endif

    #ifdef cFWM_TEMPERATURE
        temperature_stringval( val );
        XMLCon.data ( temperature_name(), val );
    #endif

    #ifdef cFWM_STACK
        stack_stringval( val );
        XMLCon.data ( stack_name(), val );
    #endif

    Serial::send ("</weather>\n");
}
```

[illegible]

Sensor integration also crosscuts actuator code, an interaction between optional features!

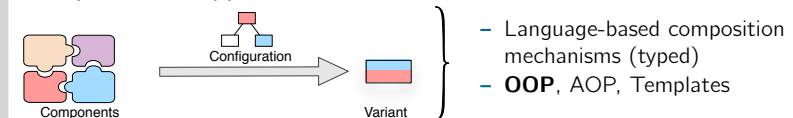
I4WeaterMon (CPP): Evaluation

General

- ❶ Separation of concerns (SoC) ❌
 - ❷ Resource thriftiness ✅
- Operational
- ❸ Granularity (✅)
 - Components implement only the functionality of a single feature, but contain integration code for other optional features.
 - ❹ Economy ✅
 - All features is bound at compile time.
 - ❺ Pluggability ❌
 - Sensor integration crosscuts main program and actuator implementation.
 - ❻ Extensibility ❌
 - New actuators require extension of main program.
 - New sensors require extension of main program and existing actuators.

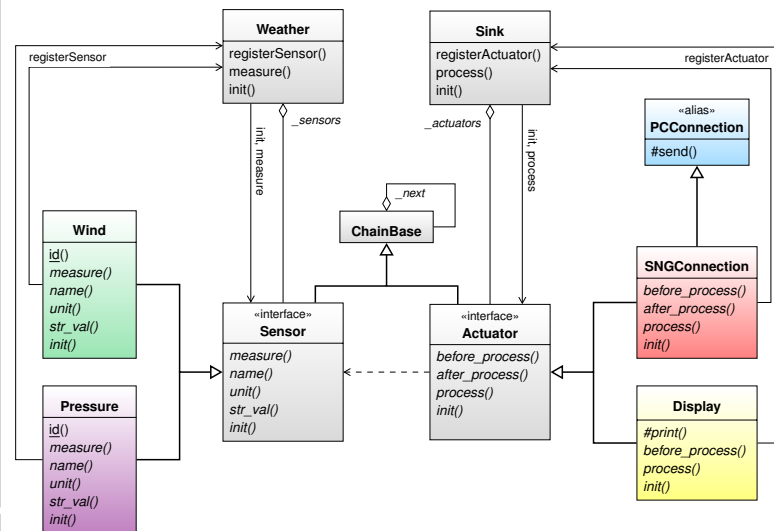
Implementation Techniques: OOP

- Compositional Approaches



- Object-oriented programming languages provide means for loose coupling by generalization and OO design patterns
 - Interfaces
 - ↪ type substitutability (optional/alternative features)
 - Observer-Pattern
 - ↪ quantification (cumulative feature groups)
 - Implicit code execution by global instance construction
 - ↪ self integration (optional features)

I4WeatherMon (OOP): Design (Excerpt)



I4WeaterMon (OOP): Evaluation

General

① Separation of concerns (SoC) ✓

② Resource thriftiness ?

Operational

③ Granularity ✓

- Every component is either a base class or implements functionality of a single feature only.

④ Economy (✓)

- Run-time binding and run-time type information is used only where necessary to achieve SoC.

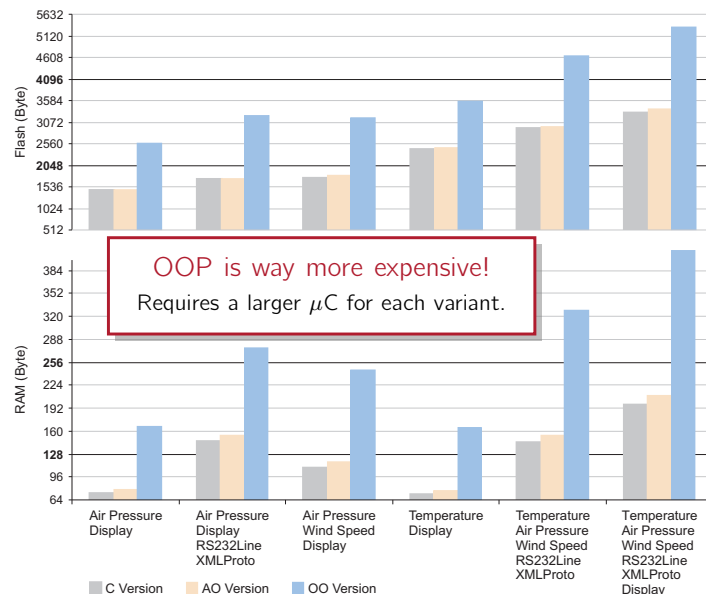
⑤ Pluggability ✓

- Sensors and actuators integrate themselves by design patterns and global instance construction.

⑥ Extensibility ✓

- “Plug & Play” of sensor and actuator implementations.

I4WeaterMon: CPP vs. OOP – Footprint



OOP is way more expensive!
Requires a larger μ C for each variant.

■ C Version ■ AO Version ■ OO Version

I4WeaterMon: CPP vs. OOP – Footprint

variant	version	text	data	bss	stack	= flash	= RAM	time (ms)
Air Pressure, Display	C	1392	30	7	34	1422	71	1.21
	AO	1430	30	10	38	1460	78	1.21
	OO	2460	100	22	44	2560	166	1.29
Air Pressure, Display, RS232Line, XMLProto	C	1578	104	7	34	1682	145	60.40
	AO	1622	104	12	38	1726	154	59.20
	OO	3008	206	26	44	3214	276	60.80
Air Pressure, Wind Speed, Display	C	1686	38	14	55	1724	107	2.96
	AO	1748	38	18	61	1786	117	2.96
	OO	3020	146	33	65	3166	244	3.08
Temperature, Display	C	2378	28	8	34	2406	70	1.74
	AO	2416	28	11	38	2444	77	1.73
	OO	3464	98	23	44	3562	165	1.82
Temperature, Wind Speed,	C	2804	90	17	35	2894	142	76.40
Air Pressure, RS232Line,	AO	2858	90	23	41	2948	154	76.40
XMLProto	OO	4388	248	39	41	4636	328	76.40
Temperature, Wind Speed,	C	3148	122	17	57	3270	196	79.60
Air Pressure, RS232Line,	AO	3262	122	24	63	3384	209	77.60
XMLProto, Display	OO	5008	300	44	67	5308	411	80.00

Implementation Techniques: Summary

- CPP: minimal hardware costs – but no separation of concerns
- OOP: separation of concerns – but high hardware costs
- OOP cost drivers
 - Late binding of functions (virtual functions)
 - Calls cannot be inlined (↪ *memory* overhead for small methods)
 - Virtual function tables
 - Compiler always generates constructors (for vtable initialization)
 - Dead code elimination less effective
 - Dynamic data structures
 - Static instance construction
 - Generation of additional initialization functions
 - Generation of a global constructor table
 - Additional startup-code required



Implementation Techniques: Summary

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Root of the problem:

With OOP we have to use **dynamic** language concepts to achieve loose coupling of **static** decisions.

↪ **AOP** as an alternative.



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