Concurrent Systems

Nebenläufige Systeme

IV. Critical Sections

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Subject Matter

discussion on abstract concepts as to critical sections:

race condition
- caused by a fault in a non-sequential program
- possibly effects an error of a non-sequential process
- if so, eventually effects failure of a computing system

race management
- pessimistic, sequential control at a “chokepoint”
- blocking synchronisation, lock-based
- optimistic, concurrent control on a “multi-lane road”
- non-blocking synchronisation, obstruction-free

explanation of typical patterns of critical sections in system software
- excursion to database systems: transactions, isolation (ACID properties)
- basic forms of inconsistency due to actions of simultaneous processes

Synchronisation v. Level of Abstraction of a Critical Section

i providing functionality as integral part of a critical section or
ii providing the same functionality on the basis of a critical section
Critical Sequence or Timing of Processes

Definition (race condition, race hazard)
The behaviour of a computing system, hardware or software, in which the result or progress depends on the simultaneity of processes.

- The notion has its origin in spurious behaviour of electronic circuits [10] namely when (at least) two signals race to be first in defining an output it becomes a critical race when the order of changing internal state can impact the outcome of the state machine of that circuit
- In software, the program flow discloses a fault that possibly results in:
  - Critical race
    - An error that, in turn, may cause failure of a system
  - Non-critical race
    - Unanticipated behaviour
    - E.g., the hand of the "clock app" overlaps time data
- Prevention of especially critical races is a must, implicitly or explicitly but before, the race condition behind must be even localised...

Heisenbug

A software fault (also: defect) that disappears or results in a different run-time behaviour when one attempts to probe or isolate it.

- In the minority of cases is the presence of a race condition obvious
- Necessary condition (i.e., mandatory) is a non-sequential program
- Sufficient condition are simultaneous processes of that very program
  - The sequence of all actions is defined by a partial order (cf. [9, p.17])
  - Loss of the total order of all actions makes overlapping indeterminate

Program testing can be used to show the presence of bugs, but never to show their absence! [1, p. 85]

- But formal methods and proofs of correctness are widely unrealistic here
  - Software must be designed for simultaneity from the very beginning
- Common practice is to approach the fault location by "test output"
  - But each software measure of that kind will change the time elapsed
  - As the case may be, a still present fault no longer manifest into an error occasionally, fault diagnostics ends—and one is okay with that defect...

Critical Section

Definition (following computer science folklore)
A sequence of program statements controlled by a sequential process in order to assure consistency according to instructions.

- A sequential program that describes mutual exclusive actions
  - That is to say, activities that relate to each other as if they are indivisible because no activity interrupts or overlaps, resp., the other [6, p.137]
  - A "software ELOP" that is subject to atomic execution by its processor

Definition (without anticipation of an implementation decision)
A sequence of program statements that assure consistency according to instructions even in the presence of simultaneous processes.

- A sequential or non-sequential program, according to requirements
  - Synchronisation as a constraint on the manner in which the sequence of program statements in question implements and delivers functionality
  - Separation of concerns: non-functional v. functional properties
A Matter of Reference: Reconsidered

Instruction Set Architecture Level

avant-garde: **non-blocking synchronisation** of the *push* function
- reused abstraction, for both list head and list element:
  1. `typedef struct chain {
     2.   struct chain *link; /* next list element */
     3. } chain_t;
- extended and adapted (new) *push* resulting in a non-sequential process:
  4. `void cas_push(chain_t *this, chain_t *item) {
     5.   do while (!CAS(&this->link, item->link, item));
     6. }`

CAS (*compare and swap*) blocks simultaneous processes out, shortly
- built-in function: `#define CAS __sync_bool_compare_and_swap`
  1. `atomic bool cas(type *ref, type old, type new) {
     2.   return (*ref == old) ? (*ref = new, true) : false;
     3. }`
- compiled by GCC into (x86) “lock cmpxchg1” instruction/ELOP

Operating-System Machine Level

“take a sledgehammer to crack a nut”: **blocking synchronisation**
- extended (new) abstraction used to represent the list head:
  1. `typedef struct mutex_chain {
     2.   chain_t head;
     3.   pthread_mutex_t lock;
     4. } mutex_chain_t;`
- extended and adapted (new) *push* resulting in a sequential process:
  5. `void mutex_push(mutex_chain_t *this, chain_t *item) {
     6.   pthread_mutex_lock(&this->lock);
     7.   item->link = this->head.link;
     8.   this->head.link = item;
     9.   pthread_mutex_unlock(&this->lock);`

lock blocks simultaneous processes out from *push*, till after *unlock*

2(Ger.) *mit Kanonen auf Spatzen schießen.*

A Matter of Reference

Separation of Concerns

Provide the wanted **functionality** in a first step and consider different implementation variants of that very functionality in a second step.

by way of example, LIFO\(^1\) storing (*push*) with a singly-linked list
- abstraction used to represent both the list head and a list element:
  1. `typedef struct chain {
     2.   struct chain *link; /* next list element */
     3. } chain_t;
- prepend specified *item* to *this* list (stack policy):
  4. `void push(chain_t *this, chain_t *item) {
     5.   item->link = this->link; /* make head follow item */
     6.   this->link = item; /* make item new head */
     7. }`

beware of simultaneous processes: race condition in *push* (cf. p.30)

\(^1\)last in, first out

Instruction Set Architecture Level

Level 2 Mutual Exclusion

**atomic instruction**

application programming level

operating-system machine level

instruction set architecture level

push

lock unlock

atomic instruction

push

push

non-blocking synchronisation

blocking synchronisation

push (left-hand) employs lock to “stonewall” simultaneous processes
- it also needs to rely on an atomic instruction\(^3\) to implement the lock
  - the sequential process lasts from that very instruction till after *unlock*
alternatively (right-hand), *push* does not lock simultaneous processes
- nevertheless, to this end, it needs to rely on an atomic instruction as well
  - but the sequential process lasts only for the duration of that instruction

push is a **physical** (left-hand) or **logical** (right-hand) critical section

\(^3\)Atomic write or atomic read-modify-write, depending on the lock protocol.
The Problem of Locks

- locks are not composable
- locks are prone to livelocks or deadlocks, resp.
- locks rely on programmers to strictly follow conventions
- locks are a synchronisation measure of global program property

beyond that:
- locks increase sequentiality or decrease concurrency, resp.
- locks are prone to priority violation or inversion, resp.
- locks rather waste computing time
- locks are rather coarse-grained...

This includes all variants of locks as well as other concepts of blocking synchronisation, particularly binary semaphore, mutex, or bolt variable resp.

Devoid of Obstruction

Definition (Optimistic Concurrency Control [8])

Method of coordination for the purpose of updating shared data by mainly relying on transaction backup as control mechanisms.

simplified, a transaction is an “all or nothing” approach of computing
- each action on shared data must either complete in its entirety or have no effect—except the time elapsed or energy consumed
- in doing so, these actions must also adhere to a defined isolation level

the method establishes the basis for non-blocking synchronisation

Devoid of Obstruction Continues

- validation and, possibly, write are an “indivisible action” (cf. p. 11)

Transaction

Definition (cf. “logical critical section” on p. 12)

Entity of one or more independent units of work and by means of which data integrity is ensured on the basis of well-defined rules.

transactional processing of shared data is differentiated as follows:
- pessimistic
  - data integrity is ensured by a lock-based protocol
  - typically, exclusive and shared locks are distinguished
  - prone to performance reduction and deadlock
- optimistic
  - data integrity is ensured by a validation-based protocol
  - thereby, a transaction is structured into several phases
    - read and execute, validate, and write or rollback (retry)
  - prone to performance reduction if too many rollbacks
- semi-optimistic
  - block the actions of a transaction when integrity rules could be violated (lock-based approach)
  - otherwise, delay integrity rule checking (i.e., validation) to the end similar to the optimistic approach

transactions may be concurrent, but not necessarily the work units

ACID Properties

Fundamental rules for an atomic transaction to establish well-defined system behaviour in the presence of faults and simultaneous actions.

  - atomicity
    - a transaction either happens or it does not
    - either all are bound by the contract or none are
  - consistency
    - each successful transaction commits only legal results
    - a transaction must obey legal protocols
  - isolation
    - events within a transaction must be hidden from other transactions running concurrently
    - and the key for it is synchronisation [2]
  - durability
    - once a transaction is committed, it cannot be abrogated
    - even in the event of power loss, crashes, or errors

the isolation property is particularly important for concurrent systems
- it has a large impact on the degree of concurrency that can be achieved
- synchronisation paradigms decide upon the loss of concurrency, even too
  - along with the trade-off between synchronisation granularity and frequency
Separation of **simultaneous transactions** in a manner that none of them falls into an undefined state or causes permanent inconsistencies.

- basic forms of **inconsistency due to concurrency** [3, p. 431]:
  - non-repeatable read
    - repeated read actions deliver different values
  - dirty read
    - not yet committed data is already (early) read
  - lost update
    - already committed data is overwritten

- advanced read/write conflict: delayed use of “state-contingent data”
  - inconsistent read
    - same search criteria apply to different data sets

**Data race patterns** that remain valid beyond data base systems

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**Non-Repeatable Read**

When the same read operation consecutively executed by a process on a shared data set may deliver different results.

- assuming that \( i \) may be manipulated by a simultaneous process:

```c
int twofold() {
    extern volatile int i;
    return i + i;
}
```

- apparently correct, but...

  - risk of wrong operation

**Solution Statement (rank-order priority, ROP)**

1. reduction to hardware ELOP, 2. non-blocking, or 3. blocking synchronisation.

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**Inconsistent Read**

When the value computed on the basis of the results of several read operations consecutively executed by a process would be different at the time the value is actually used by that process.

- assuming that \( string \) is reduced/enlarged by a simultaneous process:

```c
char string[80];

int fill(char c) {
    int i;
    for (i = 0; i < 80; i++) {
        if (!string[i]) {
            string[i] = c;
            return i;
        }
    }
    return -1;
}
```

- apparently correct, but...

  - that \( i \) identified the first free entry in line 6

  - must no longer hold in line 7

  - risk of error propagation

**Solution Statement (ROP)**

1. non-blocking or
2. blocking synchronisation.
Dirty Read

When the same uncommitted shared variable is read by a process and written by another one, simultaneously.

- assuming that the ASM part is run by two simultaneous processes:
  - reading of uncommitted data: counting revisited [9, p.14–15]

C/C++
1
   i ++;

ASM
2
   movl i, %eax
3
   addl $1, %eax
4
   movl %eax, i

- apparently correct, but...
  - risk of wrong reading (cf. p. 31)

Solution Statement (ROP)
1. reduction to hardware ELOP, 2. non-blocking, or 3. blocking synchronisation.

Lost Update

When the same uncommitted shared variable is written by processes simultaneously without having noticed prior writes of each other.

- assuming that vary and init are run by own simultaneous processes:

```c
int total = 0;

int vary(int i) {
    return total += i;
}

void init(int i) {
    total = i;
}
```

- apparently correct, but...
  - the old value of i can be read by both processes (line 2)
  - before the new value is written to i by any of them (line 4)
  - risk of blind writes

Solution Statement: same as “dirty read”, but this problem is not serializable
Non-sequential and sequential execution results in different states (cf. p.32).

Lost Wakeup

When a process identified a waiting condition and will seek blocking simultaneously to the invalidation of the condition by another process.

- assuming that both sections are run by two interacting processes:

```c
while (this -> load == 0) {
    await (this);
}

if (this -> load ++ == 0) {
    cause (this);
}
```

- apparently correct, but...
  - lines 3–4 can overlap adversely with lines 1–2
  - unblocking (line 4) sidesteps the process that will block (line 2)
  - risk of everlasting block

Solution Statement (ROP)
1. non-blocking or 2. blocking synchronisation.

“Time-of-Check to Time-of-Use” Problem

When a process checks the state of a resource before using this very resource, but the state is modified interim by another process.

- assuming that file “argv[1]” is modified by a simultaneous process:

```c
#include <stdio.h>
#include <sys/stat.h>

int main(int argc, char *argv[]) {
    struct stat buf;

    if (lstat(argv[1], &buf))
        perror("lstat failed");
    else {
        printf("%s is %s", argv[1]);
        if (buf.st_size != 0)
            printf(" not 
");
        printf(" empty
");
    }
}
```

- apparently correct, but...
  - file size may change between lines 6 and 10
  - risk of false positive or negative, resp.

Solution Statement
blocking synchronisation.
Résumé

- A race condition is an adverse behaviour of a computing system
  - caused by a fault ("concurrency bug") in a non-sequential program
  - possibly effects an error of a non-sequential process
  - as a further consequence, possibly effects failure of the system
- The faulty area in the non-sequential program is a "critical section"
  - it must be protected by making pessimistic or optimistic assumptions
  - computer science folklore goes the pessimistic way: mutual exclusion
  - avant-garde takes up a position that favours an optimistic approach

In the strict sense, it is still a matter of the level of abstraction at which the folkloristic critical section appears.

- In practice, one is faced with different patterns of race conditions
  - data races: non-repeatable read, inconsistent read, dirty read, lost update
  - control flow races: lost wakeup, TOCTOU
- Problem solving should respect differentiated views and techniques
  - 1. hardware ELOP, 2. non-blocking, and 3. blocking synchronisation

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[3] **Gray, J. N.**:
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On Optimistic Methods for Concurrency Control.
Simultaneous Push Considered Harmful

<table>
<thead>
<tr>
<th>simultaneous processes</th>
</tr>
</thead>
<tbody>
<tr>
<td>push</td>
</tr>
<tr>
<td>A : push(list, X)</td>
</tr>
<tr>
<td>B : push(list, Y)</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>list</th>
<th>action</th>
<th>item</th>
<th>action</th>
<th>item</th>
</tr>
</thead>
<tbody>
<tr>
<td>Z</td>
<td>item-&gt;link = this-&gt;link</td>
<td>X → Z</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Z</td>
<td>-</td>
<td>-</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Y → Z</td>
<td>item-&gt;link = this-&gt;link</td>
<td>Y → Z</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Y</td>
<td>-</td>
<td>-</td>
<td></td>
<td></td>
</tr>
<tr>
<td>X → Z</td>
<td>this-&gt;link = item</td>
<td>X → Z</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

- assuming that the stack is implemented as singly-linked list (cf. p. 9)
- initially, Z is the only stored entry and placed on the top of stack
- **misadventure**: processes A and B simultaneously apply the stack
  - process A first attempts to push item X but gets overlapped by B
    - X already points to the top of stack, but the latter has not yet been updated
  - process B conducts its push of item Y uninterrupted, deposits its item
    - the top of stack has been updated, the stack contains two entries: Y → Z
  - process A resumes and completes its push of item X, deposits its item
    - the top of stack has been updated, the stack contains two entries: X → Z

  two push operations executed, but only one more item was stored...

Serialisability Unresolved Despite Indivisibility

**correct (indivisible) update of the global counter variable total:**

```c
#include "aaf.h"

extern int total;

int vary(int i) {
    return AAF(&total, i);
}
```

- procedural abstraction
- reduction to an ELOP: AAF
  - `add and fetch`
  - `atomic read-modify-write`
- with GCC atomic built-in function:
  ```c
  #define AAF __sync_add_and_fetch
  ```

but parallel actions `vary || init` are not equivalent to a serial schedule:

```c
movl 4(%esp), %ecx
movl %ecx, %eax
```

- `init` (cf. p. 22) may be carried out either before or after lines 11–12
  - consequently, the final value of total remains indeterminate
  - it may read i or total + i, depending on which action came first

Reading and Processing Uncommitted Data

<table>
<thead>
<tr>
<th>i++</th>
<th>simultaneous processes(^b)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>A</td>
</tr>
<tr>
<td></td>
<td>B</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>i</th>
<th>step</th>
<th>action</th>
<th>%eax</th>
<th>action</th>
<th>%eax</th>
</tr>
</thead>
<tbody>
<tr>
<td>42</td>
<td>1</td>
<td>movl i, %eax</td>
<td>42</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>42</td>
<td>2</td>
<td>addl $1, %eax</td>
<td>43</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>42</td>
<td>3</td>
<td>-</td>
<td>movl i, %eax</td>
<td>42</td>
<td>-</td>
</tr>
<tr>
<td>42</td>
<td>4</td>
<td>-</td>
<td>addl $1, %eax</td>
<td>43</td>
<td>-</td>
</tr>
<tr>
<td>43</td>
<td>5</td>
<td>-</td>
<td>movl %eax, i</td>
<td>43</td>
<td>-</td>
</tr>
<tr>
<td>43</td>
<td>6</td>
<td>movl %eax, i</td>
<td>43</td>
<td>-</td>
<td>-</td>
</tr>
</tbody>
</table>

- dirty read or lost update—tha is the legitimate question
- step 3 reads i although it was (logically) already dirtied in step 2
- step 6 writes i unaware of the update already committed in step 5
- both is true, each one ends in a reading of one less than expected
- i++ twice-executed but its value reads as only once-counted

\(^b\)Each process has a software prototype of %eax available.