Concurrent Systems

Nebenläufige Systeme

XIII. Progress Guarantee

Wolfgang Schröder-Preikschat

— for further study —



Agenda

Process Liveliness



Outline

Process Liveliness



- necessary characteristics of a synchronisation protocol for a reference system of a specific number of concurrent processes:
- i the solution must be **symmetrical** between the processes; as a result we are not allowed to introduce a static priority
- ii nothing may be assumed about the **relative speeds** of the processes; we may not even assume their speeds to be constant in time
- iii if any of the processes is stopped well outside its critical section, this is not allowed to potential **blocking** of the others
- iv if more than one process is about to enter its critical section, it must be impossible to derive for them such finite speeds, that the decision to determine which one of them will enter its critical section first is postponed until **eternity**



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- iv if more than one process is about to enter its critical section, it must be impossible to derive for them such finite speeds, that the decision to determine which one of them will enter its critical section first is postponed until **eternity**
- although originally based on mutual exclusion of those processes, the characteristics hold for non-blocking synchronisation as well



characteristics of algorithms for non-blocking synchronisation



characteristics of algorithms for **non-blocking synchronisation**:

- obstruction-free if any process eventually in isolation (i.e., absence of simultaneously interacting processes) can complete any operation in a finite number of steps [4]
 - prone to starvation of conflicting processes



characteristics of algorithms for **non-blocking synchronisation**:

- lock-free if "some process will complete an operation in a finite number of steps, regardless of the relative speeds of the processes" $[3, p. 142]^1$
 - free of starvation of at least one conflicting process



¹Originally, also referred to as "non-blocking".

characteristics of algorithms for non-blocking synchronisation:

wait-free • if "any process can complete any operation in a finite number of steps, regardless of the relative speeds of the other processes" [3, p. 7]

• free of starvation of any conflicting process



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- lock-free if "some process will complete an operation in a finite number of steps, regardless of the relative speeds of the processes" $[3, p. 142]^1$
 - free of **starvation** of at least one conflicting process

- wait-free if "any process can complete any operation in a finite number of steps, regardless of the relative speeds of the other processes" [3, p. 7]
 - free of starvation of any conflicting process
- all, no process can be blocked by delays or failures of other processes
 - that is to say, any of these procedures ensures deadlock freedom



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Transactional Computation I

```
/* shared data */
  word_t any;
2
      word_t old, new;
                                       /* own data */
3
      do new = compute(old = any); /* read */
4
      while (!CAS(&any, old, new)); /* validate/write */
5
```



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- at a first glance, this looks like lock-free progress guarantee:
 - CAS ensures that one out of possibly many conflicting processes succeeds
 - yet, which one is not determined and process overhauling² is facilitated



²A desirable property given priority-based process scheduling.

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- however, a closer look may even reveal only obstruction freedom:
 - progress guarantee stands and falls with the properties of compute stands - lock-free if *compute* is either lock- or wait-free falls - off to obstruction-free if compute is obstruction-free
 - thus, the likewise weaker property of *compute* comes out on top



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 - thus, the likewise weaker property of compute comes out on top
- strengthening of the progress guarantee at a higher level is illusionary
 - without willingness to break abstraction or black-box reuse, resp., down



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Transactional Computation II



- at a first glance, the progress guarantee is the same as before (p. 6):
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- at a first glance, the progress guarantee is the same as before (p. 6):
 - SC ensures that one out of possibly many conflicting processes succeeds
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- however, a closer look may even reveal a further dependency:
 - LL besides reading from memory, typically performs two actions:
 - i make a reservation for a hardware-dependent address range
 - ii as the case may be, remember the effective address of the location
 - SC if a reservation exists, overwrite the addressed location
 - if applicable, only if the applied address matches the remembered one
 - in any case, cancel a possibly existing reservation



```
/* shared data */
  word_t any;
      word_t new;
                                        /* own data */
3
                                        /* read */
      do new = compute(LL(&any));
      while (!SC(&any, new));
                                        /* validate/write */
5
```

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 - if applicable, only if the applied address matches the remembered one
 - in any case, cancel a possibly existing reservation
 - plain sequences of LL/SC may be obstruction-free, only (cf. p. 13)
 - exceptions (i.e., traps/interrupts) may or may not cancel reservations
 - similar may hold for specific ("manually ejected") memory operations



Table-Based Scheduling I

- bear in mind that each process also acts as a "feeder" of a CPU core
 - normally, a process releases its processor either voluntarily or involuntarily
 - it either blocks or yields, or it gets the processor revoked (preemption)



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- each feeder takes the scheduling decision in a finite number of steps:

```
process_t *elect(hoard_t *vain) {
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       process t *next;
       for (next = being(0); next < being(NPROC); next++) {</pre>
4
            if (next->state != READY)
5
                continue:
6
7
            if (CAS(&next->state, READY, READY | PENDING))
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                return next;
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       return 0;
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the scheduling loop is **bounded** by the number of process descriptors



Table-Based Scheduling II

```
int cause(event_t *this) {
1
       process t *next;
       int done = 0:
4
       while ((next = uncage(&this->wait))) {
5
            next->merit = being(ONESELF)->name;
6
            next->state = READY:
            done += 1;
8
       }
10
       return done:
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```

- uncage attempt to purge a chain item from the queue-based per-event waitlist \sim lock-free semantics in case of [5, p. 30]
 - if succeeded, coerce the pointer to the purged chain item into the pointer to the enclosing process descriptor (cf. p. 14)



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 - if succeeded, coerce the pointer to the purged chain item into the pointer to the enclosing process descriptor (cf. p. 14)
- even in case of a wait-free purge, the schedule loop is unbounded
- a former uncaged process may have been dispatched in the meantime

 → assume the process blocks on the same event while signalling (cause)
 - © wosch, thoenig

```
int cause(event_t *this) {
1
       process_t *next;
       int done = 0:
4
       while ((done < N) && (next = uncage(&this->wait))) {
5
            next->merit = being(ONESELF)->name;
6
            next->state = READY:
           done += 1;
8
       }
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       return done;
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```

a WCET³ of the schedule loop is given only with a wait-free purge • in that case: $WCET(loop) \leq N \times WCET(purge)$, thus bounded



³worst-case execution time

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- a WCET³ of the schedule loop is given only with a wait-free purge
 - in that case: $WCET(loop) < N \times WCET(purge)$, thus bounded but in case of a lock-free purge, the schedule loop is lock-free also
 - a lock-free purge implies a possibly unbounded latency until returning



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- a WCET³ of the schedule loop is given only with a wait-free purge
- in that case: WCET(loop) ≤ N × WCET(purge), thus bounded
 but in case of a lock-free purge, the schedule loop is lock-free also
 - a lock-free purge implies a possibly unbounded latency until returning
- last but not least, similar holds in case of an obstruction-free purge



³worst-case execution time

each signaller takes the scheduling decision in a finite number of steps

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            if (next->event != this)
6
7
                 continue:
8
            if (CAS(&next->event, this, 0)) {
                 next->merit = being(ONESELF)->name;
10
                 next->state = READY;
11
                 done += 1;
12
13
        }
14
15
        return done;
16
   }
17
   the scheduling loop is bounded by the number of process descriptors
```



Reference List I

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LL/SC Shallows

- Alpha if the effective addresses are not within the same naturally aligned 16-byte section, the sequence may fail or succeed
 - a reservation on a particular processor can be arbitrarily canceled by unspecified events on another processor
 - if any other memory access is executed on the given processor in between, the sequence may always fail on some implementations
 - a timer interrupt always cancels an existing reservation

- MIPS a load, store, or prefetch event executed on the issuing processor may cause the sequence to fail or succeed
 - the largest cache line in use determines the reservation granularity
- PPC6 the reservation granularity is implementation-dependent
 - exceptions (traps/interrupts) hold up an existing reservation
 - a conditional store to a "scratch" address cancels the reservation
- PPC8 ditto, but the processor grants stores only to the reserved address

If a reservation endures exceptional situations and the processor does not compare with the reservation address, the operating system must cancel the reservation in those cases.



Process-Type Coercion

```
inline void *coerce(void *ptr, int val) {
  return (void *)((unsigned)ptr - val);
}

inline process_t *uncage(waitlist_h *list) {
  chain_t *item = purge_lfs((queue_t *)list);

if (item)
  item = coerce(item, (int)&((process_t *)0)->event);

return (process_t *)item;
}
```

